

Software Design, Modelling and Analysis in UML

Lecture 2: Semantical Model

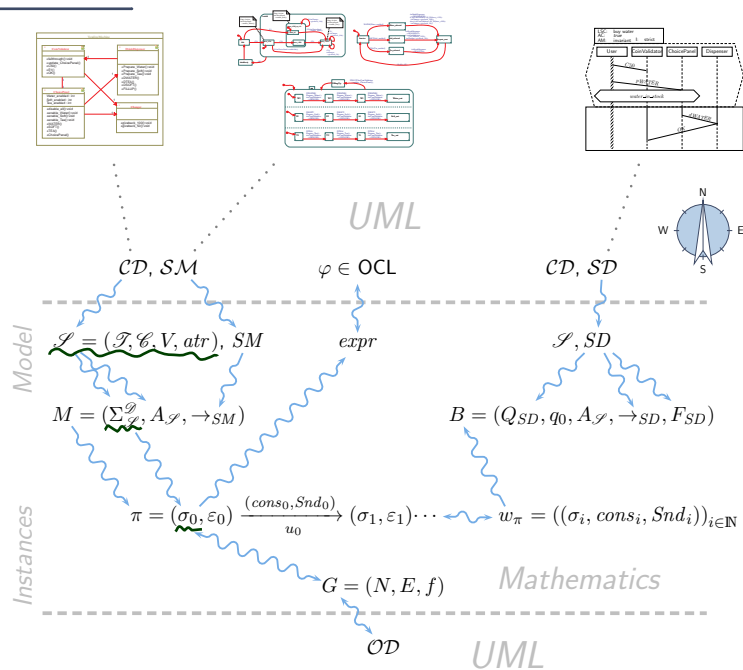
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- 2 - 2015-10-22 - main -

Course Map



- 2 - 2015-10-22 - Sieplan -

Contents & Goals

Last Lecture:

- Introduction: Motivation, Content, Formalia

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
 - What is a signature, an object, a system state, etc.?
 - What is the purpose of signature, object, etc. in the course?
 - How do Basic Object System Signatures relate to UML class diagrams?
- **Content:**
 - Basic Object System Signatures
 - Structures
 - System States

Semantical Foundation

Basic Object System Signature

Definition. A (Basic) Object System **Signature** is a quadruple

$$\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr)$$

could have chosen attr.

where

- \mathcal{T} is a set of (basic) **types**,
- \mathcal{C} is a finite set of **classes**,
- V is a finite set of **typed attributes**, i.e., each $v \in V$ has a type
 - $\tau \in \mathcal{T}$, or
 - $C_{0,1}$ or C_* , where $C \in \mathcal{C}$
 (written $v : \tau$ or $v : C_{0,1}$ or $v : C_*$),
- $atr : \mathcal{C} \rightarrow 2^V$ maps each class to its set of attributes.

C_1 C_0
 C_1 C_0

total function (arrow from atr to \mathcal{C})
powerset of V (arrow from atr to 2^V)

Note: Inspired by OCL 2.0 standard **OMG (2006)**, Annex A.

Basic Object System Signature Example

$\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr)$ where

- (basic) **types** \mathcal{T} and **classes** \mathcal{C} (both finite),
- **typed attributes** V , τ from \mathcal{T} , or $C_{0,1}$ or C_* , for some $C \in \mathcal{C}$,
- $atr : \mathcal{C} \rightarrow 2^V$ mapping classes to attributes.

Example: *set of basic types T* (arrow to $\{Int\}$)
set of classes C (arrow to $\{C, D\}$)
attributes V (arrow to $\{x : Int, p : C_{0,1}, n : C_*\}$)
attributes mapping atr (arrow to $\{C \mapsto \{p, n\}, D \mapsto \{x\}\}$)

$\mathcal{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$

attribute x has (basic) type Int (under $x : Int$)
attribute p has (derived) type C_x (under $p : C_{0,1}$)
C has attributes p and n (under $C \mapsto \{p, n\}$)
"maps to" (under $D \mapsto \{x\}$)

$$atr(C) = \{p, n\}$$

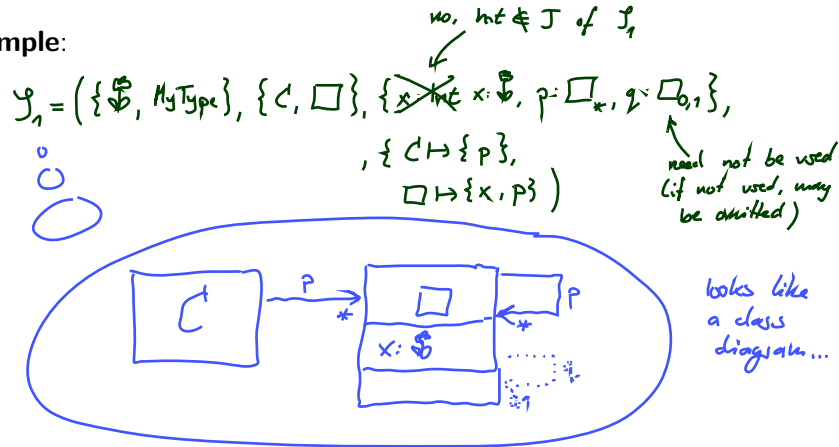
$$atr(D) = \{x\}$$

Basic Object System Signature Another Example

$\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr)$ where

- (basic) types \mathcal{T} and classes \mathcal{C} (both finite),
- typed attributes V , τ from \mathcal{T} , or $C_{0,1}$ or C_* , for some $C \in \mathcal{C}$,
- $atr : \mathcal{C} \rightarrow 2^V$ mapping classes to attributes.

Example:



- 2 - 2015-10-22 - Ssemndom -

7/34

Basic Object System Structure

Definition. A Basic Object System **Structure** of $\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr)$ is a domain function \mathcal{D} which assigns to each type a domain, i.e.

- $\tau \in \mathcal{T}$ is mapped to $\mathcal{D}(\tau)$,
- $C \in \mathcal{C}$ is mapped to an infinite set $\mathcal{D}(C)$ of (object) identities.
Note: Object identities only have the "=" operation.
- Sets of object identities for different classes are disjoint, i.e.

$$\forall C, D \in \mathcal{C} : C \neq D \rightarrow \mathcal{D}(C) \cap \mathcal{D}(D) = \emptyset.$$

- C_* and $C_{0,1}$ for $C \in \mathcal{C}$ are mapped to $2^{\mathcal{D}(C)}$.

We use $\mathcal{D}(\mathcal{C})$ to denote $\bigcup_{C \in \mathcal{C}} \mathcal{D}(C)$; analogously $\mathcal{D}(\mathcal{C}_*)$.

- 2 - 2015-10-22 - Ssemndom -

Note: We identify objects and object identities, because both uniquely determine each other (cf. OCL 2.0 standard).

8/34

Basic Object System Structure Example

Wanted: a structure for signature

$$\mathcal{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$

\mathcal{D} needs to map:

- $\tau \in \mathcal{T}$ to **some** $\mathcal{D}(\tau)$,
- $C \in \mathcal{C}$ to **some** set of identities $\mathcal{D}(C)$ (infinite, disjoint for different classes),
- C_* and $C_{0,1}$ for $C \in \mathcal{C}$: always mapped to $\mathcal{D}(C_*) = \mathcal{D}(C_{0,1}) = 2^{\mathcal{D}(C)}$.

$$\begin{aligned} \mathcal{D}(Int) &= \mathbb{Z} \\ \mathcal{D}(C) &= \mathbb{N}^+ \times \{C\} \cong \{1_C, 2_C, 3_C, \dots\} \\ \mathcal{D}(D) &= \mathbb{N}^+ \times \{D\} \cong \{1_D, 2_D, 3_D, \dots\} \\ \mathcal{D}(C_{0,1}) = \mathcal{D}(C_*) &= 2^{\mathcal{D}(C)} \\ \mathcal{D}(D_{0,1}) = \mathcal{D}(D_*) &= 2^{\mathcal{D}(D)} \end{aligned}$$

$$\begin{aligned} \mathcal{D}_1(Int) &= \{-2, -1, 0, 1, 2\} \\ \mathcal{D}_1(C) &= \{a, aa, aaa, \dots\} \\ \mathcal{D}_1(D) &= \{b, bb, bbb, \dots\} \\ &= 2^{\mathcal{D}_1(C)} \\ &= 2^{\mathcal{D}_1(D)} \end{aligned}$$

- 2 - 2015-10-22 - Ssemndom -

System State

Definition. Let \mathcal{D} be a structure of $\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr)$.

A **system state** of \mathcal{S} wrt. \mathcal{D} is a **type-consistent** mapping

$$\sigma : \mathcal{D}(\mathcal{C}) \rightarrow (V \rightarrow (\mathcal{D}(\mathcal{T}) \cup \mathcal{D}(\mathcal{C}_*)))$$

That is, for each $u \in \mathcal{D}(C)$, $C \in \mathcal{C}$, if $u \in \text{dom}(\sigma)$

- $\text{dom}(\sigma(u)) = atr(C)$
- $(\sigma(u))(v) \in \mathcal{D}(\tau)$ if $v : \tau, \tau \in \mathcal{T}$
- $(\sigma(u))(v) \in \mathcal{D}(D_*)$ if $v : D_{0,1}$ or $v : D_*$ with $D \in \mathcal{C}$

We call $u \in \mathcal{D}(\mathcal{C})$ **alive** in σ if and only if $u \in \text{dom}(\sigma)$.

We use $\Sigma_{\mathcal{S}}^{\mathcal{D}}$ to denote the set of all system states of \mathcal{S} wrt. \mathcal{D} .

set of all object identities in \mathcal{D}

partial function mapping attributes (for V) to ~~type~~ values (from $\mathcal{D}(\mathcal{T})$ and $\mathcal{D}(\mathcal{C}_*)$)

partial function

set of attributes

set of all values in \mathcal{D}

- 2 - 2015-10-22 - Ssemndom -

System State Example

$$\mathcal{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$

$$\mathcal{D}(Int) = \mathbb{Z}, \quad \mathcal{D}(C) = \{1_C, 2_C, 3_C, \dots\}, \quad \mathcal{D}(D) = \{1_D, 2_D, 3_D, \dots\}$$

Wanted: $\sigma : \mathcal{D}(\mathcal{C}) \rightarrow (V \rightarrow (\mathcal{D}(\mathcal{T}) \cup \mathcal{D}(\mathcal{C}_*)))$ such that (i) $\text{dom}(\sigma(u)) = \text{atr}(C)$, and
(ii) $\sigma(u)(v) \in \mathcal{D}(\tau)$ if $v : \tau, \tau \in \mathcal{T}$, (iii) $\sigma(u)(v) \in \mathcal{D}(C_*)$ if $v : D_*$ with $D \in \mathcal{C}$.

$$\sigma_1 = \emptyset \quad (\text{"empty function"})$$

alive in σ_1 : none

$$\sigma_2 = \left\{ \underbrace{1_C \mapsto \left\{ \begin{array}{l} p \mapsto \emptyset \\ n \mapsto \{1_C, 5_C\} \end{array} \right\}}_{\text{alive in } \sigma_2: 1_C, 5_C, 3_D}, \underbrace{5_C \mapsto \left\{ \begin{array}{l} p \mapsto \{1_C\} \\ n \mapsto \emptyset \end{array} \right\}}_{\text{not alive: everybody else}}, \underbrace{3_D \mapsto \{x \mapsto 3\}}_{\sigma(1_{7_D}) = \{x \mapsto 0\}} \right\}$$

alive in σ_2 : $1_C, 5_C, 3_D$
not alive: everybody else

$$\sigma_3 = \left\{ \underbrace{1_D \mapsto \{x \mapsto 2\}}_{\text{alive objects in } \sigma_3: 1_D, 2_D, 1_{7_D}}, \underbrace{2_D \mapsto \{x \mapsto 2\}}_{\text{alive objects in } \sigma_3: 1_D, 2_D, 1_{7_D}}, \underbrace{1_{7_D} \mapsto \{x \mapsto 0\}}_{\sigma(1_{7_D})(x) = 0} \right\}$$

alive objects in σ_3 : $1_D, 2_D, 1_{7_D}$

$$\sigma(1_{7_D}) = \{x \mapsto 0\}$$

$$\sigma(1_{7_D})(x) = 0$$

System State Example

$$\mathcal{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$

$$\mathcal{D}(Int) = \mathbb{Z}, \quad \mathcal{D}(C) = \{1_C, 2_C, 3_C, \dots\}, \quad \mathcal{D}(D) = \{1_D, 2_D, 3_D, \dots\}$$

Wanted: $\sigma : \mathcal{D}(\mathcal{C}) \rightarrow (V \rightarrow (\mathcal{D}(\mathcal{T}) \cup \mathcal{D}(\mathcal{C}_*)))$ such that (i) $\text{dom}(\sigma(u)) = \text{atr}(C)$, and
(ii) $\sigma(u)(v) \in \mathcal{D}(\tau)$ if $v : \tau, \tau \in \mathcal{T}$, (iii) $\sigma(u)(v) \in \mathcal{D}(C_*)$ if $v : D_*$ with $D \in \mathcal{C}$.

Two options:

- **Concrete, explicit** identities:

$$\sigma_2 = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, 1_D \mapsto \{x \mapsto 23\}\}.$$

! n

- **Alternative:** **symbolic** system state.

$$\sigma_3 = \{c_1 \mapsto \{p \mapsto \emptyset, n \mapsto \{c_2\}\}, c_2 \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, d \mapsto \{x \mapsto 23\}\}$$

assuming $c_1, c_2 \in \mathcal{D}(C)$, $d \in \mathcal{D}(D)$, $c_1 \neq c_2$.

System State: Spot the 10 (?) Mistakes

$$\mathcal{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$

$$\mathcal{D}(Int) = \mathbb{Z}, \quad \mathcal{D}(C) = \{1_C, 2_C, 3_C, \dots\}, \quad \mathcal{D}(D) = \{1_D, 2_D, 3_D, \dots\}$$

Wanted: $\sigma : \mathcal{D}(\mathcal{C}) \rightarrow (V \rightarrow (\mathcal{D}(\mathcal{T}) \cup \mathcal{D}(\mathcal{C}_*)))$ such that (i) $\text{dom}(\sigma(u)) = \text{atr}(C)$, and
(ii) $\sigma(u)(v) \in \mathcal{D}(\tau)$ if $v : \tau, \tau \in \mathcal{T}$, (iii) $\sigma(u)(v) \in \mathcal{D}(C_*)$ if $v : D_*$ with $D \in \mathcal{C}$.

- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{p \mapsto \emptyset, n \mapsto 1_C\}, 1_D \mapsto \{x \mapsto 2.3\}\}$.
Handwritten notes: "empty set {}" with arrow to \emptyset ; "(iii) $1_C \notin \mathcal{D}(C)$ " with arrow to 1_C ; "(ii), $2.3 \notin \mathcal{D}(Int)$ " with arrow to 2.3 .
- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{p \mapsto 1_C, n \mapsto \emptyset\}, 1_D \mapsto \{x \mapsto 23\}\}$.
Handwritten note: "(ii)" with arrow to 1_C .
- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{1_D\}\}, 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, 1_D \mapsto \{x \mapsto 22\}\}$.
Handwritten notes: "(iii) $\notin \mathcal{D}(C)$ " with arrow to 1_D ; "(i) $22 \notin \mathcal{D}(Int)$ " with arrow to 22 .
- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{n \mapsto \emptyset\}, 1_D \mapsto \{x \mapsto 1, p \mapsto \{1_C\}\}\}$.
Handwritten notes: "(i) $1_C \notin \mathcal{D}(C)$ " with arrow to 1_C ; "(i), $1 \notin \mathcal{D}(Int)$ " with arrow to 1 .
- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \{9_C\}\}\}$

Dangling References

Definition. Let $\sigma \in \Sigma_{\mathcal{D}}$ be a system state.

We say attribute $v \in V_{0,1,*}$, i.e. $v : C_{0,1}$ or $v : C_*$, in object $u \in \text{dom}(\sigma)$ has a **dangling reference** if and only if the attribute's value comprises an object which is not alive in σ , i.e. if

$$(\sigma(u))(v) \notin \text{dom}(\sigma).$$

Handwritten note: "alive objects" with arrow pointing to $\text{dom}(\sigma)$.

We call σ **closed** if and only if no attribute has a dangling reference in any object alive in σ .

Example:

- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}\}$
 $(\sigma(1_C))(n) = \{5_C\} \notin \{1_C\} = \text{dom}(\sigma)$

A Complete Example: Vending Machine



$$\mathcal{Y} = \left(\begin{array}{l} \{ \text{Bool}, \text{Nat} \}, \\ \{ \text{VM}, \text{CP}, \text{DD} \}, \\ \{ \text{cp}: (\text{P}_*, \text{dd}: \text{DD}_{0..1}, \text{wen}: \text{Bool}, \text{win}: \text{Nat}) \}, \\ \{ \text{VM} \mapsto \{ \text{cp}, \text{dd} \}, \text{CP} \mapsto \{ \text{wen} \}, \text{DD} \mapsto \{ \text{win}, \text{wen} \} \} \end{array} \right)$$

$$\mathcal{D}(\text{Bool}) = \{ \text{true}, \text{false} \}$$

$$\mathcal{D}(\text{Nat}) = \mathbb{N}$$

$$\mathcal{D}(\text{VM}) = \{ 1_{\text{VM}}, 2_{\text{VM}}, \dots \}$$

$$\mathcal{D}(\text{DD}) = \{ 1_{\text{DD}}, \dots \}$$

$$\mathcal{D}(\text{CP}) = \{ 1_{\text{CP}}, \dots \}$$

$$\mathcal{D}(\text{DD}_{0..1}) = 2^{\mathcal{D}(\text{DD})} = 2^{\{ 1_{\text{DD}}, 2_{\text{DD}}, \dots \}}$$

context DD inv:
wen imply win > 0

$$\sigma = \left\{ \begin{array}{l} \exists_{\text{VM}} \mapsto \{ \text{dd} \mapsto \{ 1_{\text{DD}} \}, \text{cp} \mapsto \{ 3_{\text{CP}}, 5_{\text{CP}} \} \}, \\ 1_{\text{DD}} \mapsto \{ \text{win} \mapsto 13, \text{wen} \mapsto \text{true} \}, \\ \exists_{\text{CP}} \mapsto \{ \text{wen} \mapsto \text{true} \}, \\ 5_{\text{CP}} \mapsto \{ \text{wen} \mapsto \text{false} \} \} \end{array} \right.$$

15/34

References

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OMG (2011b). Unified modeling language: Superstructure, version 2.4.1. Technical Report formal/2011-08-06.