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Software Design, Modelling and Analysis in UML

Lecture 8: Class Diagrams III

2015-11-26

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Contents & Goals

Last Lectures:

• completed class diagrams... except for associations.

This Lecture:

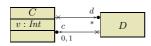
- Educational Objectives: Capabilities for following tasks/questions.
 - Please explain this class diagram with associations.
 - Which annotations of an association arrow are semantically relevant?
 - What's a role name? What's it good for?
 - What is "multiplicity"? How did we treat them semantically?
 - What is "reading direction", "navigability", "ownership", ...?
 - What's the difference between "aggregation" and "composition"?

• Content:

- Study concrete syntax for "associations".
- (Temporarily) extend signature, define mapping from diagram to signature.
- Study effect on OCL.
- Btw.: where do we put OCL constraints?



Alternative presentation:



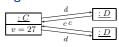
• Signature:

$$\mathcal{S} = (\{Int\}, \{C, D\}, \{v : Int, d : D_*, c : C_{0,1}\},$$
$$\{C \mapsto \{v, d\}, D \mapsto \{c\}\})$$

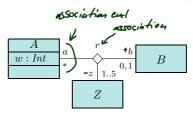
• Example system state:

$$\begin{split} \sigma &= \{1_C \mapsto \{v \mapsto 27, \mathbf{d} \mapsto \{5_D, 7_D\}\}, \\ 5_D &\mapsto \{\mathbf{d} \mapsto \{1_C\}\}, 7_D \mapsto \{\mathbf{d} \mapsto \{1_C\}\}\} \end{split}$$

• Object diagram:



• Class diagram (with ternary association):



• Signature: extend again;

represent association r with association ends $a,\,b,\,{\rm and}\,z$ (each with multiplicity, visibility, etc.)

• Example system state: (σ, λ) $\begin{cases} 3_2 & \forall \emptyset \\ 2_2 & \forall \emptyset \end{cases}$

$$\sigma = \{1_A \mapsto \{w \mapsto 13\}, 1_B \mapsto \emptyset, 1_Z \mapsto \emptyset\}$$

$$\lambda = \left\{ \begin{array}{c|c} r \mapsto \left\{ \left(1_A, 1_B, 1_Z \right) \right\} \right\} \\ \uparrow : \begin{array}{c|c} \hline \alpha & b & b \\ \hline 1_A & 1_B & 2_D \\ \hline 1_A & 1_B & 2_D \\ \hline \end{array} \right\}$$

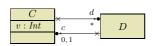
Overview

• Class diagram:





Alternative presentation:



• Signature:

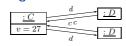
$$\mathcal{S} = (\{Int\}, \{C, D\}, \{v : Int, d : D_*, c : C_{0,1}\}, \{C \mapsto \{v, d\}, D \mapsto \{c\}\})$$

• Example system state:

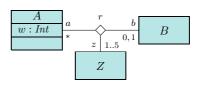
$$\sigma = \{1_C \mapsto \{v \mapsto 27, c \mapsto \{5_D, 7_D\}\},$$

$$5_D \mapsto \{d \mapsto \{1_C\}\}, 7_D \mapsto \{d \mapsto \{1_C\}\}\}$$

• Object diagram:



• Class diagram (with ternary association):



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represent association r with association ends $a,\,b,\,{\rm and}\,z$ (each with multiplicity, visibility, etc.)

• Example system state:

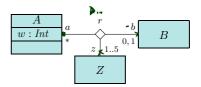
$$\sigma = \{1_A \mapsto \{w \mapsto 13\}, 1_B \mapsto \emptyset, 1_Z \mapsto \emptyset\}$$
$$\lambda = \{r \mapsto \{(1_A, 1_B, 1_Z)\}\}$$

• Object diagram: No...

Plan

- (i) Study association **syntax**.
- (ii) Extend signature accordingly.
- (iii) Define (σ, λ) system states with
 - **objects** in σ (instances of classes),
 - links in λ (instances of associations).
- (iv) Change **syntax** of OCL to refer to **association ends**.
- (v) Adjust **interpretation** *I* accordingly.
- (vi) \dots go back to the special case of $C_{0,1}$ and C_* attributes.

• Class diagram (with ternary association):



• Signature: extend again;

represent association r with association ends a, b, and z (each with multiplicity, visibility, etc.)

• Example system state:

$$\sigma = \{1_A \mapsto \{w \mapsto 13\}, 1_B \mapsto \emptyset, 1_Z \mapsto \emptyset\}$$

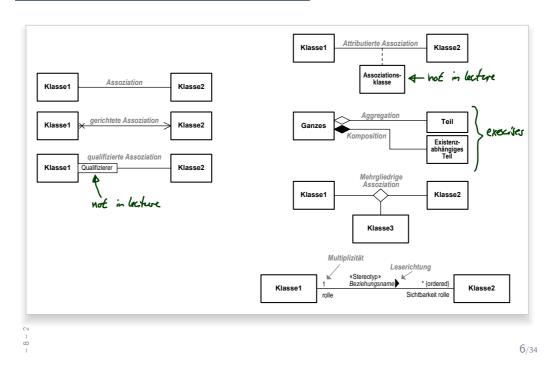
$$\lambda = \{ r \mapsto \{(1_A, 1_B, 1_Z)\} \}$$

• Object diagram: No...

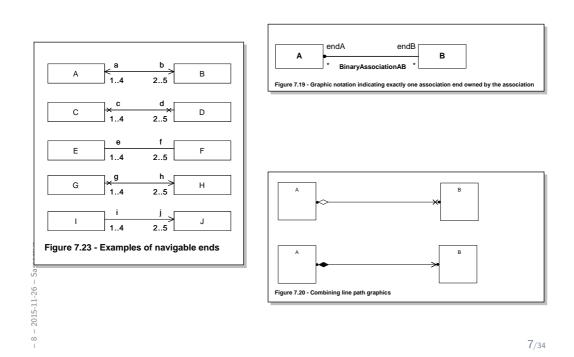
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Associations: Syntax

UML Association Syntax Oestereich (2006)



More Association Syntax (OMG, 2011b, 61;43)



So, What Do We (Have to) Cover?

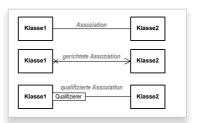
An association has

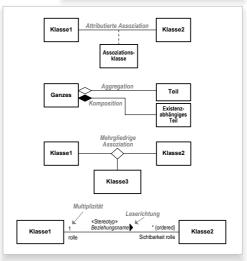
- a name.
- a reading direction, and
- at least two ends.

Each end has

- a role name,
- a multiplicity,
- a set of properties, such as unique, ordered, etc.
- · a qualifier, (not in lecture)
- a visibility,
- a navigability,
- an ownership,
- and possibly a diamond. (exclass)

Wanted: places in the signature to represent the information from the picture.





(Temporarily) Extend Signature: Associations

Only for the course of Lectures 08/09 we assume that each element in V is

- either a basic type attribute $\langle v:T,\xi,expr_0,P_v\rangle$ with $T\in\mathcal{T}$ (as before),
- or an association of the form

assucation

- $n \ge 2$ (at least two ends),
- r, $role_i$ are just names, $C_i \in \mathscr{C}$, $1 \le i \le n$,
- the multiplicity μ_i is an expression of the form

$$\mu ::= N..M \mid N..* \mid \mu, \mu \tag{N, M \in \mathbb{N}}$$

- P_i is a set of properties (as before),
- $\xi \in \{+, -, \#, \sim\}$ (as before),
- $\nu_i \in \{\times, -, >\}$ is the navigability,
- $o_i \in \mathbb{B}$ is the ownership.

- N for N..N,
- * for 0..* (use with care!)

(Temporarily) Extend Signature: Associations

Only for the course of Lectures 08/09 we assume that each element in V is

- either a basic type attribute $\langle v:T,\xi,expr_0,P_v\rangle$ with $T\in \mathscr{T}$ (as before),
- or an association of the form

$$\begin{split} \langle r: & \quad \langle role_1: C_1, \mu_1, P_1, \xi_1, \nu_1, o_1 \rangle, \\ & \vdots \\ & \quad \langle role_n: C_n, \mu_n, P_n, \xi_n, \nu_n, o_n \rangle \rangle \end{split}$$

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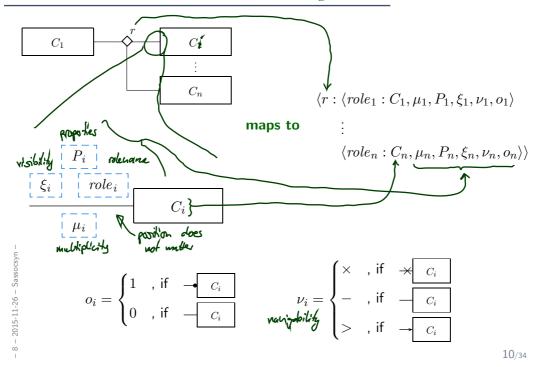
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- $\nu_i \in \{\times, -, >\}$ is the navigability,
- $o_i \in \mathbb{B}$ is the ownership.

Multiplicity abbreviations:

- \bullet N for N..N,
- * for 0..* (use with care!)

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From Association Lines to Extended Signatures



Association Example



Signature:

Te:
$$S = \{\{but\}, \{C,D\}, \{x: but, \}$$

$$\langle r: \langle c:C, 0.*, \{unique\}, -, x, 1 \rangle$$

$$\langle n:D, 0.*, \{ubuque\}, +, >, 0 \rangle \rangle$$

$$\{C \mapsto \emptyset, D \mapsto \{x\}\}\}$$

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What If Things Are Missing?

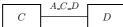
Most components of associations or association end may be omitted. For instance (OMG, 2011b, 17), Section 6.4.2, proposes the following rules:

• Name: Use

$$A - \langle C_1 \rangle - \cdots - \langle C_n \rangle$$

if the name is missing.

Example:



for



- Reading Direction: no default.
- Role Name: use the class name at that end in lower-case letters

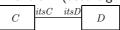
Example:



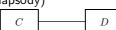
for



Other convention: (used e.g. by modelling tool Rhapsody)



for



What If Things Are Missing?

• Multiplicity: 1

In my opinion, it's safer to assume 0..1 or \ast (for $0..\ast)$ if there are no fixed, written, agreed conventions ("expect the worst")



• Properties: Ø

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• Visibility: public

• Navigability and Ownership: not so easy. (OMG, 2011b, 43)



"Various options may be chosen for showing navigation arrows on a diagram.

In practice, it is often convenient to suppress some of the arrows and crosses and just show exceptional situations:

- Show all arrows and x's. Navigation and its absence are made completely explicit.
- Suppress all arrows and x's. No inference can be drawn about navigation.
 This is similar to any situation in which information is suppressed from a view.
- Suppress arrows for associations with navigability in both directions, and show arrows only for associations with one- way navigability.
 - In this case, the two-way navigability cannot be distinguished from situations where there is no navigation at all; however, the latter case occurs rarely in practice."

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Wait, If Omitting Things...

• ...is causing so much trouble (e.g. leading to misunderstanding), why does the standard say "In practice, it is often convenient..."?

Is it a good idea to trade convenience for precision/unambiguity?

It depends.

- Convenience as such is a legitimate goal.
- In UML-As-Sketch mode, precision "doesn't matter", so convenience (for writer) can even be a primary goal.
- In UML-As-Blueprint mode, precision is the primary goal.
 And misunderstandings are in most cases annoying.

But: (even in UML-As-Blueprint mode)

If all associations in your model have multiplicity *, then it's probably a good idea not to write all these *'s.

So: tell the reader about your convention and leave out the *'s.

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Temporarily (Lecture 8/9) Extended Signature

```
Definition. An (Extended) Object System Signature (with Associations) is a quadruple \mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr) where

• ...

• each element of V is

• either a basic type attribute \langle v:T,\xi,expr_0,P_v\rangle with T\in\mathscr{T}

• or an association of the form
 \langle r: \quad \langle role_1:C_1,\mu_1,P_1,\xi_1,\nu_1,o_1\rangle, \\ \vdots \\  \langle role_n:C_n,\mu_n,P_n,\xi_n,\nu_n,o_n\rangle\rangle 

• ...

• atr:\mathscr{C}\to 2^{\{v\in V\mid v:T,\ T\in\mathscr{T}\}} maps each class to its set of basic type (!) attributes.
```

In other words:

- only basic type attributes "belong" to a class (may appear in atr(C)),
- associations are not "owned" by a particular class (do not appear in any atr(C)), but "live on their own".

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Associations: Semantics

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Recall: We consider associations of the following form:

$$\langle r: \langle role_1: C_1, \mu_1, P_1, \xi_1, \nu_1, o_1 \rangle, \dots, \langle role_n: C_n, \mu_n, P_n, \xi_n, \nu_n, o_n \rangle \rangle$$

Only these parts are relevant for extended system states:

$$\langle r: \langle role_1: C_1, _, P_1, _, _, _ \rangle, \ldots, \langle role_n: C_n, _, P_n, _, _, _ \rangle$$

(recall: we assume $P_1 = P_n = \{\text{unique}\}$).

The UML standard thinks of associations as **n-ary relations** which "**live on their own**" in a system state.

That is, **links** (= association instances)

- do not belong (in general) to certain objects (in contrast to pointers, e.g.)
- are "first-class citizens" next to objects,
- are (in general) **not** directed (in contrast to pointers).

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Links in System States

$$\langle r: \langle role_1: C_1, \neg, P_1, \neg, \neg, \neg \rangle, \dots, \langle role_n: C_n, \neg, P_n, \neg, \neg, \neg \rangle$$

Only for the course of lectures 8 / 9 we change the definition of system states:

Definition. Let \mathscr{D} be a structure of the (extended) signature with associations $\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$.

A system state of ${\mathscr S}$ wrt. ${\mathscr D}$ is a pair (σ,λ) consisting of

a type-consistent mapping (as before)

 wy basic type attribute

 where

 $\sigma: \mathscr{D}(\mathscr{C}) \nrightarrow (atr(\mathscr{C}) \nrightarrow \mathscr{D}(\mathscr{T})),$

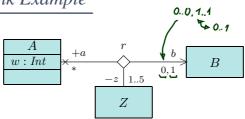
• a mapping λ which maps each association $\langle r:\langle role_1:C_1\rangle,\ldots,\langle role_n:C_n\rangle\rangle\in V$ to a **relation**

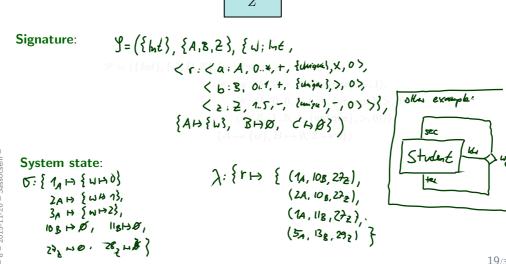
$$\lambda(r) \subseteq \mathscr{D}(C_1) \times \cdots \times \mathscr{D}(C_n)$$

(i.e. a set of type-consistent n-tuples of identities).

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Association / Link Example





Associations and OCL

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Recall: OCL syntax as introduced in Lecture 3, interesting part:

```
expr ::= \dots \quad | r_1(expr_1) : \tau_C \to \tau_D \qquad \qquad r_1 : D_{0,1} \in atr(C) 
| r_2(expr_1) : \tau_C \to Set(\tau_D) \qquad \qquad r_2 : D_* \in atr(C)
```

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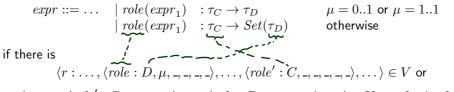
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OCL and Associations: Syntax

Recall: OCL syntax as introduced in Lecture 3, interesting part:

$$expr ::= \dots \quad | r_1(expr_1) : \tau_C \to \tau_D \qquad \qquad r_1 : D_{0,1} \in atr(C)$$
$$| r_2(expr_1) : \tau_C \to Set(\tau_D) \qquad \qquad r_2 : D_* \in atr(C)$$

Now becomes



 $\langle r: \ldots, \langle role': C, _, _, _, _ \rangle, \ldots, \langle role: D, \mu, _, _, _ \rangle, \ldots \rangle \in V, \quad role \neq role'.$

Note:

- Association name as such does not occur in OCL syntax, role names do.
- $\bullet \ expr_1$ has to denote an object of a class which "participates" in the association.

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```
\begin{array}{c|c} expr::=\dots & | \ role(expr_1) & : \tau_C \to \tau_D & \mu = 0..1 \ \text{or} \ \mu = 1 \text{--} \text{\bf 1} \\ & | \ role(expr_1) & : \tau_C \to Set(\tau_D) & \text{otherwise} \\ \\ \text{if there is} & \\ & \langle r:\dots,\langle role:D,\mu,\_,\_,\_,\rangle,\dots,\langle role':C,\_,\_,\_,\_,\rangle,\dots\rangle \in V \ \text{or} \\ & \langle r:\dots,\langle role':C,\_,\_,\_,\_,\rangle,\dots,\langle role:D,\mu,\_,\_,\_,\_\rangle,\dots\rangle \in V, role \neq role'. \end{array}
```



Figure 7.21 - Binary and ternary associations (OMG, 2011b, 44).

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OCL and Associations: Semantics

Recall:

$$\text{Assume } expr_1:\tau_C \text{ for some } C\in\mathscr{C}. \text{ Set } u_1:=I[\![expr_1]\!](\sigma,\beta)\in\mathscr{D}(T_C).$$

$$\bullet I[\![r_1(expr_1)]\!](\sigma,\beta):=\begin{cases} u & \text{, if } u_1\in \operatorname{dom}(\sigma) \text{ and } \sigma(u_1)(r_1)=\{u\}\\ \bot & \text{, otherwise} \end{cases}$$

$$\bullet I[\![r_2(expr_1)]\!](\sigma,\beta):=\begin{cases} \sigma(u_1)(r_2) & \text{, if } u_1\in \operatorname{dom}(\sigma)\\ \bot & \text{, otherwise} \end{cases}$$

Now needed:

$$I[role(expr_1)]((\sigma,\lambda),\beta)$$

• We cannot simply write $\sigma(u)(role)$.

Recall: role is (for the moment) not an attribute of object u (not in atr(C)).

• What we have is $\lambda(r)$ (with association name r, not with role name role!).

$$\langle r:\ldots,\langle role:D,\mu,_,_,_\rangle,\ldots,\langle role':C,_,_,_,_\rangle,\ldots\rangle$$

But it yields a set of n-tuples, of which **some** relate u and some instances of D.

ullet role denotes the position of the D's in the tuples constituting the value of r.

References

Oestereich, B. (2006). Analyse und Design mit UML 2.1, 8. Auflage. Oldenbourg, 8. edition.

OMG (2011a). Unified modeling language: Infrastructure, version 2.4.1. Technical Report formal/2011-08-05.

OMG (2011b). Unified modeling language: Superstructure, version 2.4.1. Technical Report formal/2011-08-06.