Software Design, Modelling and Analysis in UML Lecture 14: Hierarchical State Machines I

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Prof. Dr. Andreas Podelski, Dr. Bernd Westphal

Albert-Ludwigs-Universität Freiburg, Germany

Content

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- Missing Pieces: Create and Destroy Transformers
- Putting It All Together (Again)
- -• Initial States
- └-• **Consistency** wrt. OCL Constraints
- Hierarchical State Machines
- Overview
- Abstract Syntax: States
- └_● pseudo-states, regions, ...
- -• (Legal) System Configurations
- -• Abstract Syntax: Transitions
- -• Enabledness of Fork/Join Transitions
 - └-(● scope, priority, maximality, ...

Putting It All Together

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Initial States

Recall: a labelled transition system is (S, A, \rightarrow, S_0) . We have

- S: system configurations (σ, ε)
- \rightarrow : labelled transition relation $(\sigma, \varepsilon) \xrightarrow{(cons,Snd)} (\sigma', \varepsilon')$.

Wanted: initial states S_0 .

Proposal:

Require a (finite) set of **object diagrams** $\mathscr{O}\mathscr{D}$ as part of a UML model

(CD, SM, OD).



And set

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$$S_0 = \{ (\sigma, \varepsilon) \mid \sigma \in G^{-1}(\mathcal{OD}), \quad \mathcal{OD} \in \mathscr{OD}, \quad \varepsilon \text{ empty} \}.$$

Other Approach: (used by Rhapsody tool) multiplicity of classes (plus initialisation code). We can read that as an abbreviation for an object diagram.

The semantics of the UML model

$$\mathcal{M} = (\mathscr{CD}, \mathscr{SM}, \mathscr{OD})$$

where

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- some classes in *CD* are stereotyped as 'signal' (standard), some signals and attributes are stereotyped as 'external' (non-standard),
- there is a 1-to-1 relation between classes and state machines,
- \mathscr{OD} is a set of object diagrams over \mathscr{CD} ,

is the transition system (S, A, \rightarrow, S_0) constructed on the previous slide(s).

The computations of \mathcal{M} are the computations of (S, A, \rightarrow, S_0) .

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context D inv

OCL Constraints and Behaviour

- Let $\mathcal{M} = (\mathscr{CD}, \mathscr{SM}, \mathscr{OD})$ be a UML model.
- We call \mathcal{M} consistent iff, for each OCL constraint $expr \in Inv(\mathscr{CD})$,

 $\sigma \models expr$ for each "reasonable point" (σ, ε) of computations of \mathcal{M} .

(Cf. tutorial for discussion of "reasonable point".)



Transformer: Create

abstract syntax	concrete syntax			
$\mathtt{create}(C, expr, v)$	expr.v := new C			
intuitive semantics				
Create an object of class C and assign it to attribute v of the object denoted by expression <i>expr</i> .				
well-typedness				
$expr: T_D, v \in atr(D),$	$expr: T_D, v \in atr(D),$			
$atr(C) = \{ \langle v_1^{\star} : T_1^{\star}, expr_i^0 \rangle \mid 1 \le i \le n \}$				
semantics				
observables				
(error) conditions				
$I[\![expr]\!](\sigma,eta)$ not define	d.			

$$x = (\text{new C}) \cdot y + (\text{new D}) \cdot 2;$$

$$can be written as$$

$$tup_{1} := \text{new C};$$

$$tup_{5} := \text{new D};$$

$$x = tup_{1}, y + tup_{5} \cdot 2;$$

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Transformer: Create

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$expr: T_D, v \in atr(D),$				
$atr(C) = \{ \langle v_1 : T_1, expr_i^0 \rangle \mid 1 \le i \le n \}$				
semantics				
observables				
(error) conditions				
$I[[expr]](\sigma,\beta)$ not defined.				

• We use an "and assign"-action for simplicity – it doesn't add or remove expressive power, but moving creation to the expression language raises all kinds of other problems since then expressions would need to modify the system state.

 Also for simplicity: no parameters to construction (~ parameters of constructor). Adding them is straightforward (but somewhat tedious).

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How To Choose New Identities?

- **Re-use**: choose any identity that is not alive **now**, i.e. not in dom(σ).
 - Doesn't depend on history.
 - May "undangle" dangling references may happen on some platforms.
- Fresh: choose any identity that has not been alive ever, i.e. not in $dom(\sigma)$ and any predecessor in current run.
 - Depends on history.
 - Dangling references remain dangling could mask "dirty" effects of platform.

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abstract syntax	concrete syntax
destroy(expr)	
intuitive semantics	
Destroy the object denoted by expression	on expr.
well-typedness	
$expr:T_C$, $C\in \mathscr{C}$	
semantics	
observables	
$Obs_{\texttt{destroy}}[u_x] = \{(u_x, \bot, (+, \emptyset),$	$u)\}$
(error) conditions	
$I[[expr]](\sigma,\beta)$ not defined.	

What to Do With the Remaining Objects?

Assume object u_0 is destroyed...

- object u_1 may still refer to it via association r:
 - allow dangling references?
 - or remove u_0 from $\sigma(u_1)(r)$?
- object u_0 may have been the last one linking to object u_2 :
 - leave u_2 alone?
 - or remove u_2 also? (garbage collection)
- Plus: (temporal extensions of) OCL may have dangling references.

Our choice: Dangling references and no garbage collection!

This is in line with "expect the worst", because there are target platforms which don't provide garbage collection – and models shall (in general) be correct without assumptions on target platform.

But: the more "dirty" effects we see in the model, the more expensive it often is to analyse. Valid proposal for simple analysis: monotone frame semantics, no destruction at all.

abstract syntax	concrete syntax
destroy(expr)	
intuitive semantics	
Destroy the object denoted by expression	l expr.
well-typedness	
$expr:T_C$, $C\in \mathscr{C}_{\mathbb{R}}$,	
semantics function re	striction
$t_{\texttt{destroy}(exp_{p}')}[u_{x}](\sigma, \varepsilon) = \{(\sigma', \varepsilon')\} \epsilon'$	$= [uJ(\varepsilon)]$
where $\sigma' = \sigmaert_{\mathrm{dom}(\sigma) \setminus \{u\}}$ with $u = I \llbracket expr$	$]\!](\sigma, u_x).$
observables	
$Obs_{\texttt{destroy}(expr)}[u_x] = \{(+, u)\}$	
(error) conditions	
$I[[expr]](\sigma, u_x)$ not defined.	



Destroy Transformer Example



Hierarchical State-Machines

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The Full Story

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UML distinguishes the following kinds of states:

	example		example
simple state	$\overbrace{ \begin{array}{c} s_1 \\ entry/act_1^{entry} \\ do/act_1^{do} \\ exit/act_1^{exit} \\ \end{array} }^{s_1}$	pseudo-state initial (shallow) history	Ĥ
	$\begin{pmatrix} E_1/act_{E_1} \\ \dots \\ E_n/act_{E_n} \end{pmatrix}$	deep history	(H*)
final state		fork/join	\rightarrow
composite state	8	junction, choice	, _
OR	Image: Signature Image: Signature Image: Signature Image: Signature Image: Signature Imag		0
AND		exit point	\otimes
		terminate	×
		submachine state	$\boxed{S:s}$

Blessing or Curse...?



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Blessing or Curse...?



Representing All Kinds of States



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Representing All Kinds of States

• So far:

$$(S, s_0, \rightarrow), \quad s_0 \in S, \quad \rightarrow \subseteq S \times (\mathscr{E} \cup \{_\}) \times Expr_{\mathscr{I}} \times Act_{\mathscr{I}} \times S$$

• From now on: (hierarchical) state machines

$$(S, kind, region, \rightarrow, \psi, annot)$$

where

•	$S \supseteq \{top\}$ is a finite set of states	(new: <i>top</i>),
•	$\textit{kind}: S \rightarrow \{\texttt{st}, \texttt{init}, \texttt{fin}, \texttt{shist}, \texttt{dhist}, \texttt{fork}, \texttt{join}, \texttt{junc}, \texttt{choi}, \texttt{ent}, \texttt{exi}, \texttt{term} \}$	
	is a function which labels states with their kind,	(new)
•	$region:S \rightarrow 2^{2^S}$ is a function which characterises the regions of a state,	(new)
•	\rightarrow is a set of transitions,	(changed)
•	$\psi: (\stackrel{\cdot}{ ightarrow}) \xrightarrow{!} 2^S imes 2^S$ is an incidence function, and	(new)
•	annot : $(\stackrel{\iota}{\to}) \to (\mathscr{E} \cup \{_\}) \times Expr_{\mathscr{S}} \times Act_{\mathscr{S}}$ provides an annotation for each transition.	(new)

(s₀ is then redundant - replaced by proper state (!) of kind 'init'.)

Well-Formedness: Regions

	$\in S$	kind	$region \subseteq 2^S, S_i \subseteq S$	$child \subseteq S$
final state	s	fin	Ø	Ø
pseudo-state	s	init,	Ø	Ø
simple state	s	st	Ø	Ø
composite state	s	st	$\{S_1,\ldots,S_n\}, n \ge 1$	$S_1 \cup \cdots \cup S_n$
implicit top state	top	st	$\{S_1\}$	S_1

- Final and pseudo states must not comprise regions.
- States $s \in S$ with kind(s) = st may comprise regions.

Naming conventions can be defined based on regions:

- No region: simple state.
- One region: OR-state.

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pseudo-state

- Two or more regions: AND-state.
- Each state (except for *top*) must lie in exactly one region.
- Note: The region function induces a child function.
- Note: Diagramming tools (like Rhapsody) can ensure well-formedness.



$(S, kind, region, ightarrow, \psi, annot)$					
	example	$\in S$	kind	region	
simple state	S	5	st	Ø	
final state	\odot_{ℓ}	Ŷ	fin	Ø	
composite state					
OR	s [\$1] [\$2] [\$3]	S	st	{ { 5,, 52, 53 } }	
AND	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	2	sE	{ { { { { { { { { { { { { { { { { { {	
submachine state	(later) -	-	-		

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(s,kind(s)) for short

q.•, ...

From UML to Hierarchical State Machine: By Example

From UML to Hierarchical State Machine: By Example



- ... denotes $(S, kind, region, \rightarrow, \psi, annot)$ with
- $S = \{top, s_1, s, s_2\}$
- $kind = \{top \mapsto \mathsf{st}, s_1 \mapsto \mathsf{init}, s \mapsto \mathsf{st}, s_2 \mapsto \mathsf{fin}\}$
- or $(S, kind) = \{(top, st), (s_1, init), (s, st), (s_2, fin)\}$
- region = { $top \mapsto \{\{s_1, s, s_2\}\}, s_1 \mapsto \emptyset$, $s \mapsto \emptyset$, $s_2 \mapsto \emptyset$ }
- \rightarrow , ψ , annot: in a minute.

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Recall

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- The type of (implicit attribute) st is from now on a set of states, i.e. $\mathscr{D}(S_{M_C}) = 2^S$
- A set $S_1 \subseteq S$ is called (legal) state configuration if and only if
 - $top \in S_1$, and
 - for each region R of a state in S₁, exactly one (non pseudo-state) element of R is in S₁, i.e.

 $\forall s \in S_1 \, \forall R \in region(s) \bullet | \{s \in R \mid kind(s) \in \{st, fin\}\} \cap S_1| = 1.$

• Examples:



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Recall



• For simplicity, we consider transitions with (possibly) multiple sources and targets, i.e.

$$\psi: (\to) \to (2^S \setminus \emptyset) \times (2^S \setminus \emptyset)$$

• For instance,



translates to

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$$(S, kind, region, \underbrace{\{t_1\}}_{\rightarrow}, \underbrace{\{t_1 \mapsto (\{s_2, s_3\}, \{s_5, s_6\})\}}_{\psi}, \underbrace{\{t_1 \mapsto (tr, gd, act)\}}_{annot})$$

• Naming convention: $\psi(t) = (source(t), target(t))$.

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Orthogonal States

- Two states $s_1, s_2 \in S$ are called orthogonal, denoted $s_1 \perp s_2$, if and only if
 - they "live" in different regions of one AND-state, i.e.

$$\exists s, region(s) = \{S_1, \dots, S_n\}, 1 \le i \ne j \le n : s_1 \in child(S_i) \land s_2 \in child(S_j),$$

Legal Transitions

A hierarchical state-machine $(S, kind, region, \rightarrow, \psi, annot)$ is called **well-formed** if and only if for all transitions $t \in \rightarrow$,

- source (and destination) states are pairwise orthogonal, i.e.
 - $\forall s, s' \in source(t) \ (\in target(t)) \bullet s \perp s',$
- the top state is neither source nor destination, i.e.
 - $top \notin source(t) \cup source(t)$.

Recall: final states are not sources of transitions.

Example:

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Plan

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- Transitions involving non-pseudo states.
- Initial pseudostate, final state.
- Entry/do/exit actions, internal transitions.
- History and other pseudostates, the rest.



Tell Them What You've Told Them...

- For the Create Action, we have two main choices:
 - re-use identities ("nasty semantics"),
 - use fresh identities ("clean semantics", depends on history).
 Similar for Destroy.
- Hierarchical State Machines introduce Regions.
 - Thereby, states can lie within states as children.
 - The implicit variable *st* becomes set-valued.
- Transitions may now have
 - multiple source states, multiple destination states,
 - but need to adhere to well-formedness conditions.
- Enabledness of a set (!) of transitions is a bit tricky to define (→ scope, priority, maximality).
- Steps are a proper generalisation of core state machines.

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References

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References

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