



Tutorial for Cyber-Physical Systems - Discrete Models Exercise Sheet 8

Exercise 1: Liveness properties

Let P and P' be liveness properties over AP . Prove or disprove the following claims:

- (a) $P \cup P'$ is a liveness property.
- (b) $P \cap P'$ is a liveness property.

Recall Definition 3.33 from the book:

An LT property P over AP is a liveness property iff $\text{pref}(P) = (2^{AP})^*$.

Exercise 2: LT properties

Recall Exercise 2 from Sheet 6. We considered seven LT properties with $AP = \{a, b\}$.

- (a) State for each of these properties which of them are invariants, which are safety properties, which are liveness properties, and which are neither.
(Hint: some properties fall into several classes.)
- (b) For those properties P which are neither a safety nor a liveness property, find a decomposition of $P = P_s \cap P_l$ into a safety and a liveness property. Use ω -regular expressions to describe P_s and P_l .

For your reference, we list the properties again below.

- (i) Always (at any point of time) a or b holds.
- (ii) Always (at any point of time) a and b holds.
- (iii) Never b holds before a holds.
- (iv) Every time a holds there will be eventually a point of time where b holds.
- (v) At exactly three points of time, a holds.
- (vi) If there are infinitely many points of time where a holds, then there are infinitely many points of time where b holds.
- (vii) There are only finitely many points of time where a holds.

Exercise 3: Traces

Let TS_{Sem} and TS_{Pet} be the transition systems for the semaphore-based mutual exclusion algorithm (Example 2.24 in the book) and Peterson's algorithm (Example 2.25), respectively. Let $AP = \{wait_i, crit_i \mid i = 1, 2\}$. Prove or disprove:

$$\text{Traces}(TS_{Sem}) = \text{Traces}(TS_{Pet}).$$

If the property does not hold, it is sufficient to give a trace of one transition system that is not a trace of the other transition system.