

# *Real-Time Systems*

## *Lecture 5: Duration Calculus III*

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# Duration Calculus: Preview

- Duration Calculus is an **interval logic**.
- Formulae are evaluated in an **(implicitly given)** interval.

**Strangest operators:**  $\lceil \text{Form} \rceil$

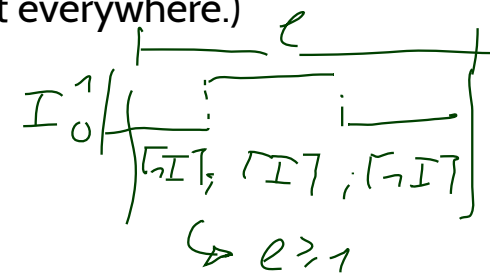
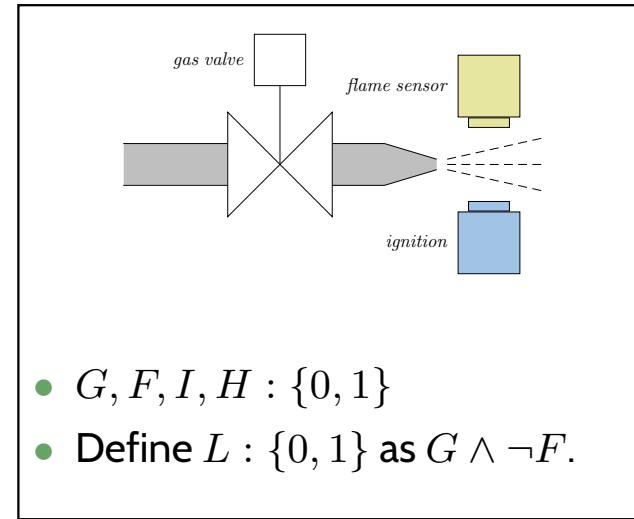
- **almost everywhere** – Example:  $\lceil G \rceil$

(Holds in a given interval  $[b, e]$  iff the gas valve is open almost everywhere.)

- **chop** – Example:  $(\lceil \neg I \rceil ; \lceil I \rceil ; \lceil \neg I \rceil) \implies \ell \geq 1$   
(Ignition phases last at least one time unit.)

- **integral** – Example:  $\ell \geq 60 \implies \int L \leq \frac{\ell}{20}$

(At most 5% leakage time within intervals of at least 60 time units.)



# Content

## Introduction

- **Observables and Evolutions**
- **Duration Calculus (DC)** ✓
- **Semantical Correctness Proofs** 5
- **DC Decidability** 6/7
- **DC Implementables**
- **PLC-Automata**
- **Timed Automata (TA)**, Uppaal
- **Networks of Timed Automata**
- **Region/Zone-Abstraction**
- **TA model-checking**
- **Extended Timed Automata**
- **Undecidability Results**

$$obs : \text{Time} \rightarrow \mathcal{D}(obs)$$

$$\langle obs_0, \nu_0 \rangle, t_0 \xrightarrow{\lambda_0} \langle obs_1, \nu_1 \rangle, t_1 \dots$$

- **Automatic Verification...**  
...whether a TA satisfies a DC formula, observer-based
- **Recent Results:**
  - **Timed Sequence Diagrams**, or **Quasi-equal Clocks**, or **Automatic Code Generation**, or ...

- **Semantics-based Correctness Proofs**

- Example: **Gas Burner Controller**
- **Theorem 2.16**: Des-1 and Des-2 is a correct design wrt. Req
- **Lemma 2.19**: Des-1 and Des-2 imply a simplified requirement Req-1
- **Some Laws of the DC Integral Operator**
- **Lemma 2.17**: Req-1 implies Req

- **Obstacles (in a Non-Ideal World)**

- requirements may be **unrealisable** without considering plant assumptions
- **intermediate** design levels
- **different observables**
- **proving correctness** may be difficult

- If time permits:  
**A Calculus for DC**

*Specification and Semantics-based Correctness Proofs  
of Real-Time Systems with DC*

# Methodology (in an ideal world)

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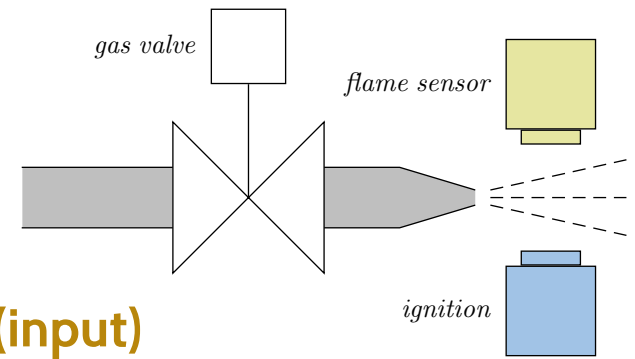
In order to **prove** a controller design **correct** wrt. a **specification**:

- (i) Choose **observables** ‘Obs’.
- (ii) Formalise the **requirements** ‘Req’ as a conjunction of DC formulae (over ‘Obs’).
- (iii) Formalise a **controller design** ‘Ctrl’ as a conjunction of DC formulae (over ‘Obs’).
- (iv) We say ‘Ctrl’ is **correct** (wrt. ‘Req’) iff

$$\models_0 \text{Ctrl} \implies \text{Req},$$

so “just” prove  $\models_0 \text{Ctrl} \implies \text{Req}$ .

# Gas Burner Revisited



(i) Choose **observables**:

- $F : \{0, 1\}$ : value 1 models “flame sensed now” **(input)**
- $G : \{0, 1\}$ : value 1 models “gas valve is open now” **(output)**
- define  $L := G \wedge \neg F$  to model **leakage**

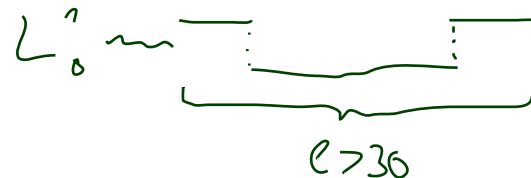
(ii) Formalise the **requirement**:

$$\text{Req} := \square(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)$$

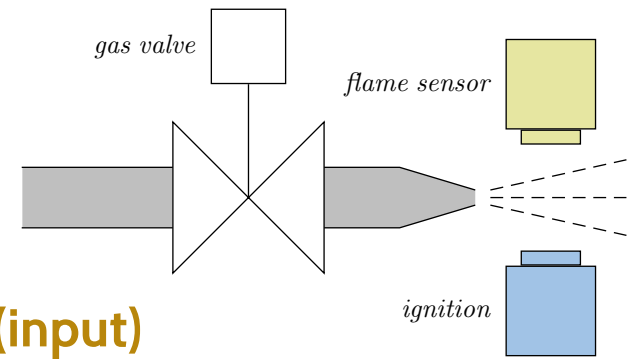
“in each interval of length at least 60 time units, at most 5% of the time leakage”

(iii) Formalise **controller design ideas**:

- Des-1 :=  $\square(\lceil L \rceil \implies \ell \leq 1)$   
 “**make** leakage phases last for at most one time unit”
- Des-2 :=  $\square(\lceil L \rceil ; \lceil \neg L \rceil ; \lceil L \rceil \implies \ell > 30)$



# Gas Burner Revisited



(i) Choose **observables**:

- $F : \{0, 1\}$ : value 1 models “flame sensed now” **(input)**
- $G : \{0, 1\}$ : value 1 models “gas valve is open now” **(output)**
- define  $L := G \wedge \neg F$  to model **leakage**

(ii) Formalise the **requirement**:

$$\text{Req} := \Box(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)$$

“in each interval of length at least 60 time units, at most 5% of the time leakage”

(iii) Formalise **controller design ideas**:

- Des-1 :=  $\Box(\lceil L \rceil \implies \ell \leq 1)$   
“**make** leakage phases last for at most one time unit”
- Des-2 :=  $\Box(\lceil L \rceil ; \lceil \neg L \rceil ; \lceil L \rceil \implies \ell > 30)$   
“**ensure**: non-leakage phases between two leakage phases last at least 30 time units”

(iv) Prove **correctness**, i.e. prove  $\models (\text{Des-1} \wedge \text{Des-2} \implies \text{Req})$ .

(Or do we want “ $\models_0$ ”...?)



# A Correct Gas Burner Controller Design

$$\text{Req} := \Box(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)$$

$$\text{Des-1} := \Box(\lceil L \rceil \implies \ell \leq 1), \quad \text{Des-2} := \Box(\lceil L \rceil ; \lceil \neg L \rceil ; \lceil L \rceil \implies \ell > 30)$$

- A **controller for the gas burner** which guarantees Des-1 and Des-2 is **correct** wrt. Req if:

$$\models (\text{Des-1} \wedge \text{Des-2} \implies \text{Req})$$

(shown in **Theorem 2.16**)

- We do prove (in **Lemma 2.19**)

$$\models (\text{Des-1} \wedge \text{Des-2}) \implies \text{Req-1.}$$

for the the **simplified requirement**

$$\text{Req-1} := \Box(\ell \leq 30 \implies \int L \leq 1).$$

(“intervals of length at most 30 time units have at most 1 time unit of accumulated leakage”)

- Showing

$$\models \text{Req-1} \implies \text{Req}$$

(in **Lemma 2.17**) completes the overall proof.

# Lemma 2.17

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## Claim:

$$\models \underbrace{\Box(\ell \leq 30 \implies \int L \leq 1)}_{\text{Req-1}} \implies \underbrace{\Box(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)}_{\text{Req}}$$

## Proof:

- Assume that 'Req-1' holds.
- Let  $L_{\mathcal{I}}$  be any interpretation of  $L$ , and  $[b, e]$  an interval with  $e - b \geq 60$ .
- We need to show that

$$20 \cdot \int L \leq \ell$$

evaluates to 'tt' on **interval**  $[b, e]$  under **interpretation**  $\mathcal{I}$  (and any **valuation**  $\mathcal{V}$ ).

- We have

$$\mathcal{I}[\![20 \cdot \int L \leq \ell]\!](\mathcal{V}, [b, e]) = \text{tt}$$

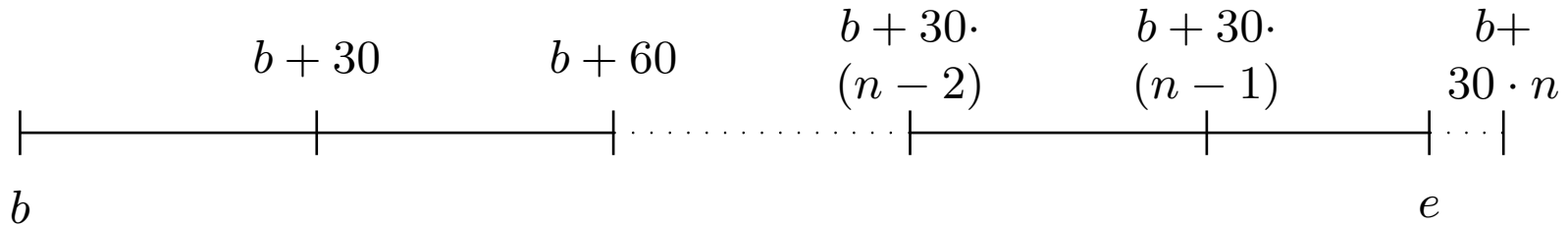
$\iff$  (by DC semantics)

$$20 \hat{\leq} \int_b^e L_{\mathcal{I}}(t) dt \hat{\leq} (e - b)$$

# Lemma 2.17 Cont'd

$$\begin{aligned} & \models \underbrace{\square(\ell \leq 30 \implies fL \leq 1)}_{\text{Req-1}} \\ & \implies \underbrace{\square(\ell \geq 60 \implies 20 \cdot fL \leq \ell)}_{\text{Req}} \end{aligned}$$

- Set  $n := \lceil \frac{e-b}{30} \rceil$ , i.e.  $n \in \mathbb{N}$  with  $n - 1 < \frac{e-b}{30} \leq n$ , and split the interval as follows:

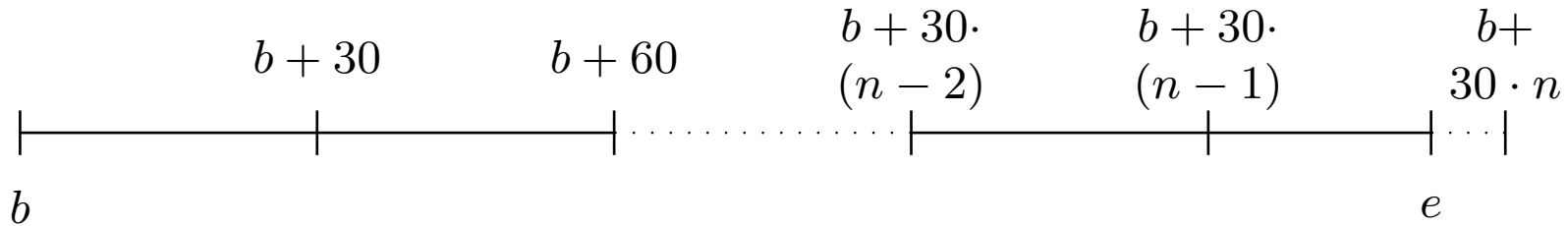


$$\begin{aligned} & 20 \cdot \int_b^e L_{\mathcal{I}}(t) dt \\ & = 20 \left( \underbrace{\sum_{i=0}^{n-2} \int_{b+30i}^{b+30(i+1)} L_{\mathcal{I}}(t) dt}_{\leq 1} + \underbrace{\int_{b+30(n-1)}^e L_{\mathcal{I}}(t) dt}_{\leq 1} \right) \\ \text{\color{blue}\{Req-1\}} & \leq \left( 20 \cdot \sum_{i=0}^{n-2} 1 \right) + (20 \cdot 1) \end{aligned}$$

# Lemma 2.17 Cont'd

$$\begin{aligned} & \models \underbrace{\square(\ell \leq 30 \implies fL \leq 1)}_{\text{Req-1}} \\ & \implies \underbrace{\square(\ell \geq 60 \implies 20 \cdot fL \leq \ell)}_{\text{Req}} \end{aligned}$$

- Set  $n := \lceil \frac{e-b}{30} \rceil$ , i.e.  $n \in \mathbb{N}$  with  $n - 1 < \frac{e-b}{30} \leq n$ , and split the interval as follows:



$$\begin{aligned} & 20 \cdot \int_b^e L_{\mathcal{I}}(t) dt \\ & = 20 \left( \sum_{i=0}^{n-2} \int_{b+30i}^{b+30(i+1)} L_{\mathcal{I}}(t) dt + \int_{b+30(n-1)}^e L_{\mathcal{I}}(t) dt \right) \end{aligned}$$

$$\{\text{Req-1}\} \leq 20 \cdot \sum_{i=0}^{n-2} 1 + 20 \cdot 1 = 20 \cdot n$$

$$\{(*)\} < 20 \cdot \left( \frac{e-b}{30} + 1 \right) = \frac{2}{3}(e-b) + 20$$

$$\{e - b \geq 60\} \leq e - b$$

□

# Some Laws of the DC Integral Operator

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## Theorem 2.18.

For all state assertions  $P$  and all real numbers  $r_1, r_2 \in \mathbb{R}$ ,

(i)  $\models \int P \leq \ell$ ,

(ii)  $\models \left( \int P = r_1 \right) ; \left( \int P = r_2 \right) \implies \left( \int P = (r_1 + r_2) \right)$

(iii)  $\models [\neg P] \implies \int P = 0$ ,

(iv)  $\models [] \implies \int P = 0$ .

# Lemma 2.19

- (i)  $\models f P \leq \ell$ ,      (iii)  $\models [\neg P] \implies f P = 0$ ,
- (ii)  $\models (f P = r_1); (f P = r_2) \implies f P = r_1 + r_2$ ,
- (iv)  $\models [] \implies f P = 0$ .

**Claim:**

$$\models \overbrace{(\Box([L] \implies \ell \leq 1))}^{\text{Des-1}} \wedge \overbrace{\Box([L]; [\neg L]; [L] \implies \ell > 30)}^{\text{Des-2}} \implies \overbrace{\Box(\ell \leq 30 \implies f L \leq 1)}^{\text{Req-1}}$$

**Proof:**

$$\ell \leq 30$$

{Des-2}  $\implies$

$$\begin{aligned} & [] \\ & \vee [L]; ([] \vee [\neg L]) \quad \text{---} \\ & \vee [\neg L]; ([] \vee [L]) \quad \text{---} \\ & \vee [\neg L]; [L]; [\neg L] \quad \text{---} \end{aligned}$$

$\ell = 29$

# Lemma 2.19

(i)  $\models f P \leq \ell$ ,      (iii)  $\models [\neg P] \implies f P = 0$ ,  
(ii)  $\models (f P = r_1); (f P = r_2) \implies f P = r_1 + r_2$ ,  
(iv)  $\models \square \implies f P = 0$ .

**Claim:**

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**Proof:**

$$\ell \leq 30$$

{Des-2}  $\implies$

$$\begin{aligned} & \square \\ & \vee [L]; (\square \vee [\neg L]) \\ & \vee [\neg L]; (\square \vee [L]) \\ & \vee [\neg L]; [L]; [\neg L] \end{aligned}$$

{Des-1}  $\implies$

$$\begin{aligned} & \square \\ & \vee (\ell \leq 1); (\square \vee [\neg L]) \\ & \vee [\neg L]; (\square \vee (\ell \leq 1)) \\ & \vee [\neg L]; (\ell \leq 1); [\neg L] \end{aligned}$$

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**Proof:**

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$$\begin{aligned} & \square \\ & \vee [L]; (\square \vee [\neg L]) \\ & \vee [\neg L]; (\square \vee [L]) \\ & \vee [\neg L]; [L]; [\neg L] \end{aligned}$$

{Des-1}  $\implies$

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{(i)}  $\implies$

$$\begin{aligned} & \square \\ & \vee (f L \leq 1); (\square \vee [\neg L]) \\ & \vee [\neg L]; (\square \vee (f L \leq 1)) \\ & \vee [\neg L]; (f L \leq 1); [\neg L] \end{aligned}$$



# Lemma 2.19

(i)  $\models f P \leq \ell$ ,      (iii)  $\models [\neg P] \implies f P = 0$ ,  
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**Proof:**

$$\ell \leq 30$$

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$$\begin{aligned} & \square \\ & \vee [L]; (\square \vee [\neg L]) \\ & \vee [\neg L]; (\square \vee [L]) \\ & \vee [\neg L]; [L]; [\neg L] \end{aligned}$$

$$\{\text{(iv), (iii)}\} \implies f L = 0$$

$$\begin{aligned} & \vee (f L \leq 1); (f L = 0 \vee \cancel{f L = 0}) \\ & \vee f L = 0; (f L = 0 \vee (f L \leq 1)) \\ & \vee f L = 0; (f L \leq 1); f L = 0 \end{aligned}$$

{Des-1}  $\implies$

$$\begin{aligned} & \square \\ & \vee (\ell \leq 1); (\square \vee [\neg L]) \\ & \vee [\neg L]; (\square \vee (\ell \leq 1)) \\ & \vee [\neg L]; (\ell \leq 1); [\neg L] \end{aligned}$$

{(i)}  $\implies$

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# Lemma 2.19

(i)  $\models f P \leq \ell$ ,    (iii)  $\models \lceil \neg P \rceil \implies f P = 0$ ,  
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**Proof:**

$$\ell \leq 30$$

{Des-2}  $\implies$

$$\lceil \rceil$$

$$\vee \lceil L \rceil; (\lceil \rceil \vee \lceil \neg L \rceil)$$

$$\vee \lceil \neg L \rceil; (\lceil \rceil \vee \lceil L \rceil)$$

$$\vee \lceil \neg L \rceil; \lceil L \rceil; \lceil \neg L \rceil$$

{Des-1}  $\implies$

$$\lceil \rceil$$

$$\vee (\ell \leq 1); (\lceil \rceil \vee \lceil \neg L \rceil)$$

$$\vee \lceil \neg L \rceil; (\lceil \rceil \vee (\ell \leq 1))$$

$$\vee \lceil \neg L \rceil; (\ell \leq 1); \lceil \neg L \rceil$$

{(i)}  $\implies$

$$\lceil \rceil$$

$$\vee (f L \leq 1); (\lceil \rceil \vee \lceil \neg L \rceil)$$

$$\vee \lceil \neg L \rceil; (\lceil \rceil \vee (f L \leq 1))$$

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$$\vee f L = 0; (f L = 0 \vee (f L \leq 1))$$

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{(ii)}  $\implies f L = 0$

$$\vee f L \leq 1 + 0$$

$$\vee f L \leq 0 + 1$$

$$\vee f L \leq 0 + 1 + 0$$

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{Des-1}  $\implies$

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{(i)}  $\implies$

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$$\{(iv), (iii)\} \implies f L = 0$$

$$\begin{aligned} & \vee (f L \leq 1); (f L = 0 \vee f L = 0) \\ & \vee f L = 0; (f L = 0 \vee (f L \leq 1)) \\ & \vee f L = 0; (f L \leq 1); f L = 0 \end{aligned}$$

$$\{(ii)\} \implies f L = 0$$

$$\begin{aligned} & \vee f L \leq 1 + 0 \\ & \vee f L = 0 + 1 \\ & \vee f L \leq 0 + 1 + 0 \end{aligned}$$

$$\implies f L \leq 1$$

□

- **Semantics-based Correctness Proofs**

- Example: **Gas Burner Controller**
- **Theorem 2.16**: Des-1 and Des-2 is a correct design wrt. Req ✓
- **Lemma 2.19**: Des-1 and Des-2 imply a simplified requirement Req-1
- **Some Laws of the DC Integral Operator**
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- **Obstacles (in a Non-Ideal World)**

- requirements may be **unrealisable** without considering plant assumptions
- **intermediate** design levels
- **different observables**
- **proving correctness** may be difficult

- If time permits:  
**A Calculus for DC**

# *Obstacles in Non-Ideal World*

# Methodology: The World is Not Ideal...

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- (i) Choose a collection of **observables** 'Obs'.
- (ii) Provide **specification** 'Req' (conjunction of DC formulae over 'Obs').
- (iii) Provide a description 'Ctrl' of the **controller** (DC formula over 'Obs').
- (iv) Prove 'Ctrl' **correct** (wrt. 'Req'), i.e. prove  $\models \text{Ctrl} \implies \text{Req}$ .

That looks **too simple to be practical**.

Typical **obstacles**:

- (i) It may be **impossible** to realise 'Req' if it doesn't consider properties of the plant.
- (ii) There are typically intermediate **design levels** between 'Req' and 'Ctrl'.
- (iii) 'Req' and 'Ctrl' may use **different observables**.
- (iv) Proving validity of the implication is **not trivial**.

## (i) Assumptions As A Form of Plant Model

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- Often the controller will (or can) operate correctly only under some **assumptions**.
- For instance, with a **level crossing**
  - we may assume an **upper bound** on the **speed of approaching trains**,  
(otherwise we'd need to close the gates arbitrarily fast)
  - we may assume that trains are **not arbitrarily slow** in the crossing,  
(otherwise we can't make promises to the road traffic)
- We shall **specify such assumptions** as a DC formula 'Asm' on the **input observables** and verify correctness of 'Ctrl' wrt. 'Req' by proving validity (from 0) of

$$\text{Ctrl} \wedge \text{Asm} \implies \text{Req}$$

- Shall we **care** whether 'Asm' is satisfiable?

## (ii) Intermediate Design Levels

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- A **top-down development approach** may involve
  - Req – **specification/requirements**
  - Des – **design**
  - Ctrl – **implementation**
- Then **correctness** is established by proving validity of

$$\text{Ctrl} \implies \text{Des}$$

– (1)

and

$$\text{Des} \implies \text{Req}$$

① ~~###~~ (2)

(and then concluding 'Ctrl  $\implies$  Req' by transitivity).

- Any preference on the order (of (1) and (2))?



### (iii): Different Observables

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- Assume, 'Req' uses **more abstract observables**  $\text{Obs}_A$  and 'Ctrl' **more concrete observables**  $\text{Obs}_C$ .
- **For instance:**
  - in  $\text{Obs}_A$ : only consider **one gas valve, open or closed** –  $(G : \{0, 1\})$
  - in  $\text{Obs}_C$ : may consider **two valves and intermediate positions**, for instance, to react to different heating requests –  $G_i : \{0, 1, 2, 3\}, i \in \{1, 2\}$
- To **prove correctness**,
  - we need information **how the observables are related**,
  - an **invariant** which **links** the data values of  $\text{Obs}_A$  and  $\text{Obs}_C$ .
- **If** we're given the linking invariant as a DC formula, say 'Link $_{C,A}$ ', **then** proving correctness of 'Ctrl' wrt. 'Req' amounts to proving

$$\models_0 \text{Ctrl} \wedge \text{Link}_{C,A} \implies \text{Req}.$$

- For instance,  $\text{Link}_{C,A} := \top \vee [G \iff (G_1 > 0 \vee G_2 > 0)]$ .

# Obstacle (iv): How to Prove Correctness?

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## Main options:

- **by hand** on the basis of DC semantics (as demonstrated before),
- using **proof rules** from a calculus ( $\rightarrow$  later),
- sometimes a **general theorem** may fit (e.g. cycle times of PLC automata),
- **algorithms** as in Uppaal ( $\rightarrow$  later).

# *Tell Them What You've Told Them. . .*

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- **Design ideas** for the behaviour of real-time system controllers can also be described using DC formulae.
- The **correctness** of a design idea wrt. requirements can principally be proven “on foot” (using the DC semantics and analysis results).
- This approach is not limited to over-simplified (?) **gas burner** controllers:
  - Consider **plant assumptions**.
  - Use **intermediate designs** in a step-by-step development.
  - Link **different observables** by invariants.
  - Consider other **proof techniques**.

# *References*

# References

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Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.