

# *Real-Time Systems*

## *Lecture 9: DC Implementables II*

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Dr. Bernd Westphal

Albert-Ludwigs-Universität Freiburg, Germany

- **Correctness Proof**  
for the Gas Burner Implementables
- **Now where's the implementation?**
- **Programmable Logic Controllers (PLC)**
  - How do they **look like**?
  - What's **special** about them?
  - The **read/compute/write** cycle of PLC
- **Example: Stutter Filter**
  - **Structured Text** example
  - Other IEC 61131-3 programming languages
- **PLC Automata**
  - **Example: Stutter Filter**
  - **PLCA Semantics** by example
  - **Cycle time**

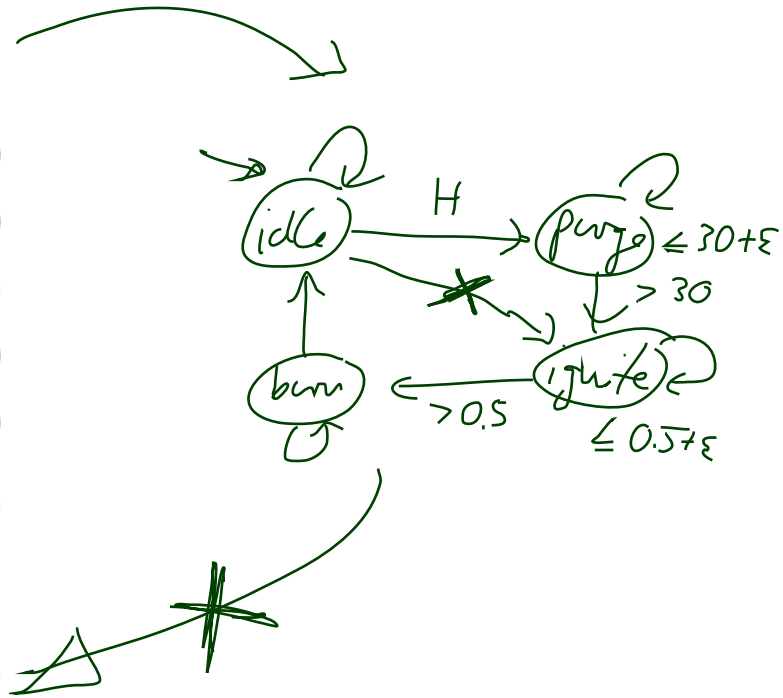
## *Recall: Specification of a Gas Burner Controller*

# Gas Burner Controller: The Complete Specification

$C: \{ \text{idle, purge, ignite, burn} \}$

## Controller: (local)

- $\lceil \rceil \vee \lceil \text{idle} \rceil ; \text{true},$  (Init-1)
- $\lceil \text{idle} \rceil \longrightarrow \lceil \text{idle} \vee \text{purge} \rceil$  (Seq-1)
- $\lceil \text{purge} \rceil \longrightarrow \lceil \text{purge} \vee \text{ignite} \rceil$  (Seq-2)
- $\lceil \text{ignite} \rceil \longrightarrow \lceil \text{ignite} \vee \text{burn} \rceil$  (Seq-3)
- $\lceil \text{burn} \rceil \longrightarrow \lceil \text{burn} \vee \text{idle} \rceil$  (Seq-4)
- $\lceil \text{purge} \rceil \xrightarrow{30+\epsilon} \lceil \neg \text{purge} \rceil$  (Prog-1)
- $\lceil \text{ignite} \rceil \xrightarrow{0.5+\epsilon} \lceil \neg \text{ignite} \rceil$  (Prog-2)
- $\lceil \neg \text{purge} \rceil ; \lceil \text{purge} \rceil \xrightarrow{\leq 30} \lceil \text{purge} \rceil$  (Stab-2)
- $\lceil \neg \text{ignite} \rceil ; \lceil \text{ignite} \rceil \xrightarrow{\leq 0.5} \lceil \text{ignite} \rceil$  (Stab-3)
- $\lceil \text{idle} \wedge H \rceil \xrightarrow{\epsilon} \lceil \neg \text{idle} \rceil$  (Syn-1)
- $\lceil \text{burn} \wedge (\neg H \vee \neg F) \rceil \xrightarrow{\epsilon} \lceil \neg \text{burn} \rceil$  (Syn-2)
- $\lceil \neg \text{idle} \rceil ; \lceil \text{idle} \wedge \neg H \rceil \longrightarrow \lceil \text{idle} \rceil$  (Stab-1)
- $\lceil \text{idle} \wedge \neg H \rceil \longrightarrow_0 \lceil \text{idle} \rceil$  (Stab-1-init)
- $\lceil \neg \text{burn} \rceil ; \lceil \text{burn} \wedge H \wedge F \rceil \longrightarrow \lceil \text{burn} \rceil$  (Stab-4)



# Gas Burner Controller: The Complete Specification

## Controller: (local)

$$\begin{aligned} & \llbracket \rrbracket \vee \llbracket \text{idle} \rrbracket ; \text{true}, & \text{(Init-1)} \\ \llbracket \text{idle} \rrbracket & \longrightarrow \llbracket \text{idle} \vee \text{purge} \rrbracket & \text{(Seq-1)} \\ \llbracket \text{purge} \rrbracket & \longrightarrow \llbracket \text{purge} \vee \text{ignite} \rrbracket & \text{(Seq-2)} \\ \llbracket \text{ignite} \rrbracket & \longrightarrow \llbracket \text{ignite} \vee \text{burn} \rrbracket & \text{(Seq-3)} \\ \llbracket \text{burn} \rrbracket & \longrightarrow \llbracket \text{burn} \vee \text{idle} \rrbracket & \text{(Seq-4)} \\ \llbracket \text{purge} \rrbracket & \xrightarrow{30+\epsilon} \llbracket \neg \text{purge} \rrbracket & \text{(Prog-1)} \\ \llbracket \text{ignite} \rrbracket & \xrightarrow{0.5+\epsilon} \llbracket \neg \text{ignite} \rrbracket & \text{(Prog-2)} \\ \llbracket \neg \text{purge} \rrbracket ; \llbracket \text{purge} \rrbracket & \xrightarrow{\leq 30} \llbracket \text{purge} \rrbracket & \text{(Stab-2)} \\ \llbracket \neg \text{ignite} \rrbracket ; \llbracket \text{ignite} \rrbracket & \xrightarrow{\leq 0.5} \llbracket \text{ignite} \rrbracket & \text{(Stab-3)} \\ \llbracket \text{idle} \wedge H \rrbracket & \xrightarrow{\epsilon} \llbracket \neg \text{idle} \rrbracket & \text{(Syn-1)} \\ \llbracket \text{burn} \wedge (\neg H \vee \neg F) \rrbracket & \xrightarrow{\epsilon} \llbracket \neg \text{burn} \rrbracket & \text{(Syn-2)} \\ \llbracket \neg \text{idle} \rrbracket ; \llbracket \text{idle} \wedge \neg H \rrbracket & \longrightarrow \llbracket \text{idle} \rrbracket & \text{(Stab-1)} \\ \llbracket \text{idle} \wedge \neg H \rrbracket & \longrightarrow_0 \llbracket \text{idle} \rrbracket & \text{(Stab-1-init)} \\ \llbracket \neg \text{burn} \rrbracket ; \llbracket \text{burn} \wedge H \wedge F \rrbracket & \longrightarrow \llbracket \text{burn} \rrbracket & \text{(Stab-4)} \end{aligned}$$

## Gas Valve: (output)

$$\begin{aligned} & \llbracket \rrbracket \vee \llbracket \neg G \rrbracket ; \text{true} & \text{(Init-4)} \\ \llbracket G \wedge (\text{idle} \vee \text{purge}) \rrbracket & \xrightarrow{\epsilon} \llbracket \neg G \rrbracket & \text{(Syn-3)} \\ \llbracket \neg G \wedge (\text{ignite} \vee \text{burn}) \rrbracket & \xrightarrow{\epsilon} \llbracket G \rrbracket & \text{(Syn-4)} \\ \llbracket G \rrbracket ; \llbracket \neg G \wedge (\text{idle} \vee \text{purge}) \rrbracket & \longrightarrow \llbracket \neg G \rrbracket & \text{(Stab-6)} \\ & \llbracket \neg G \wedge (\text{idle} \vee \text{purge}) \rrbracket \longrightarrow_0 \llbracket \neg G \rrbracket & \text{(Stab-6-init)} \\ \llbracket \neg G \rrbracket ; \llbracket G \wedge (\text{ignite} \vee \text{burn}) \rrbracket & \longrightarrow \llbracket G \rrbracket & \text{(Stab-7)} \end{aligned}$$

## Heating Request: (input)

$$\llbracket \rrbracket \vee \llbracket \neg H \rrbracket ; \text{true}, \quad \text{(Init-2)}$$

## Flame: (input)

$$\begin{aligned} & \llbracket \rrbracket \vee \llbracket \neg F \rrbracket ; \text{true}, & \text{(Init-3)} \\ \llbracket F \rrbracket ; \llbracket \neg F \wedge \neg \text{ignite} \rrbracket & \longrightarrow \llbracket \neg F \rrbracket & \text{(Stab-5)} \\ \llbracket \neg F \wedge \neg \text{ignite} \rrbracket & \longrightarrow_0 \llbracket \neg F \rrbracket & \text{(Stab-5-init)} \end{aligned}$$

*Implementable Gas Burner Controller:  
Correctness Proof*

# Gas Burner Controller Correctness Proof

**Set** GB-Ctrl := Init-1  $\wedge$   $\dots$   $\wedge$  Stab-7  $\wedge$   $\varepsilon > 0$ .

In the following, we show

$$\models \text{GB-Ctrl} \wedge A(\varepsilon) \implies \text{Req-1}.$$

where  $A(\varepsilon)$  constrains the **reaction time** of computers executing the control program.

**Read:** **if** a program behaving like ‘GB-Ctrl’ is executed on a computer with reaction time  $\varepsilon$  such that  $A(\varepsilon)$  holds, then ‘Req’ is **satisfied** in the system.

**Recall:**

$$\text{Req} : \iff \Box(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)$$

and (cf. Olderog and Dierks (2008))

$$\models \text{Req-1} \implies \text{Req}$$

for the **simplified** requirement

$$\text{Req-1} := \Box(\ell \leq 30 \implies \int L \leq 1).$$

# Lemma 3.15

$$\models \text{GB-Ctrl} \implies \Box \left( \begin{array}{l} ([\text{idle}] \implies \int G \leq \varepsilon) \\ \wedge ([\text{purge}] \implies \int G \leq \varepsilon) \\ \wedge ([\text{ignite}] \implies \ell \leq 0.5 + \varepsilon) \\ \wedge ([\text{burn}] \implies \int \neg F \leq 2\varepsilon) \end{array} \right)$$

**Proof:** Let  $\mathcal{I}$  be an interpretation,  $\mathcal{V}$  a valuation, and  $[c, d]$  an interval with  $\mathcal{I}, \mathcal{V}, [c, d] \models \text{GB-Ctrl}$ .

Let  $[b, e] \subseteq [c, d]$ .

- **Case 1:**  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{idle}]$   
From

$$[G \wedge (\text{idle} \vee \text{purge})] \xrightarrow{\varepsilon} [\neg G] \quad (\text{Syn-3})$$

$$[G] ; [\neg G \wedge (\text{idle} \vee \text{purge})] \longrightarrow [\neg G] \quad (\text{Stab-6})$$

we can conclude

$$\mathcal{I}, \mathcal{V}, [b, e] \models \underbrace{\Box([G] \implies \ell \leq \varepsilon)}_{\text{by (Syn-3), the valve is closed within } \varepsilon \text{ time units when in 'idle'}} \wedge \underbrace{\neg \Diamond([G] ; [\neg G] ; [G])}_{\text{by (Stab-6), the valve doesn't open again when in 'idle'}}$$

Thus  $\mathcal{I}, \mathcal{V}, [b, e] \models \int G \leq \varepsilon$ .

- **Case 2:**  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{purge}]$  Analogously to case 1.



# Lemma 3.15 Cont'd

$$\text{GB-Ctrl} \implies \square \left( \begin{array}{l} ([\text{idle}] \implies f G \leq \varepsilon) \\ \wedge ([\text{purge}] \implies f G \leq \varepsilon) \\ \wedge ([\text{ignite}] \implies \ell \leq 0.5 + \varepsilon) \\ \wedge ([\text{burn}] \implies f \neg F \leq 2\varepsilon) \end{array} \right)$$

- **Case 3:**  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{ignite}]$

From

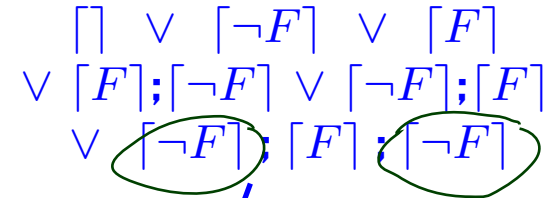
$$[\text{ignite}] \xrightarrow{0.5+\varepsilon} [\neg \text{ignite}] \quad (\text{Prog-2})$$

we can directly conclude  $\mathcal{I}, \mathcal{V}, [b, e] \models \ell \leq 0.5 + \varepsilon$ .

- **Case 4:**  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{burn}]$

From

$$\begin{array}{l} [\text{burn} \wedge (\neg H \vee \neg F)] \xrightarrow{\varepsilon} [\neg \text{burn}] \quad (\text{Syn-2}) \\ [F]; [\neg F \wedge \neg \text{ignite}] \longrightarrow [\neg F] \quad (\text{Stab-5}) \end{array}$$



we can conclude

$$\mathcal{I}, \mathcal{V}, [b, e] \models \underbrace{\square ([\neg F] \implies \ell \leq \varepsilon)}_{\text{by (Syn-2)}} \wedge \underbrace{\neg \diamond ([F]; [\neg F]; [F])}_{\text{by (Stab-5)}}$$

Thus  $\mathcal{I}, \mathcal{V}, [b, e] \models f \neg F \leq 2\varepsilon$ .

## Lemma 3.16

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$$\models \exists \varepsilon \bullet \text{GB-Ctrl} \implies \underbrace{\Box(\ell \leq 30 \implies \int L \leq 1)}_{\text{Req-1}}$$

**Proof:** Let  $\mathcal{I}, \mathcal{V}$ , and  $[b, e]$  such that  $\mathcal{I}, \mathcal{V}, [b, e] \models \text{GB-Ctrl} \wedge \ell \leq 30$ .

**Distinguish 5 cases:**

- (i)  $\mathcal{I}, \mathcal{V}, [b, e] \models \Box$  ✓
- (ii)  $\mathcal{I}, \mathcal{V}, [b, e] \models (\lceil \text{idle} \rceil ; \text{true} \wedge \ell \leq 30)$
- (iii)  $\mathcal{I}, \mathcal{V}, [b, e] \models (\lceil \text{purge} \rceil ; \text{true} \wedge \ell \leq 30)$
- (iv)  $\mathcal{I}, \mathcal{V}, [b, e] \models (\lceil \text{ignite} \rceil ; \text{true} \wedge \ell \leq 30)$
- (v)  $\mathcal{I}, \mathcal{V}, [b, e] \models (\lceil \text{burn} \rceil ; \text{true} \wedge \ell \leq 30)$

# Lemma 3.16 Cont'd

$$3.15: \text{GB-Ctrl} \implies \square \left( \begin{array}{l} ([\text{idle}] \implies f G \leq \varepsilon) \\ \wedge ([\text{purge}] \implies f G \leq \varepsilon) \\ \wedge ([\text{ignite}] \implies \ell \leq 0.5 + \varepsilon) \\ \wedge ([\text{burn}] \implies f \neg F \leq 2\varepsilon) \end{array} \right)$$

- **Case (i):**  $\mathcal{I}, \mathcal{V}, [b, e] \models \square$
- **Case (ii):**  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{idle}] ; \text{true} \wedge \ell \leq 30$

From

$$[\text{idle}] \longrightarrow [\text{idle} \vee \text{purge}] \tag{Seq-1}$$

$$[\neg \text{purge}] ; [\text{purge}] \xrightarrow{\leq 30} [\text{purge}] \tag{Stab-2}$$

we can conclude

$$\mathcal{I}, \mathcal{V}, [b, e] \models [\text{idle}] \vee [\text{idle}] ; [\text{purge}]$$

By 3.15,

$$\mathcal{I}, \mathcal{V}, [b, e] \models (f L \leq \varepsilon) \vee (f L \leq \varepsilon ; f L \leq \varepsilon)$$

hence

$$\mathcal{I}, \mathcal{V}, [b, e] \models f L \leq 2\varepsilon$$

Thus  $\boxed{\varepsilon \leq 0.5}$  is sufficient for Req-1 ( $f L \leq 1$ ) **in this case.**

# Lemma 3.16 Cont'd

$$3.15: \text{GB-Ctrl} \implies \square \left( \begin{array}{l} ([\text{idle}] \implies \int G \leq \varepsilon) \\ \wedge ([\text{purge}] \implies \int G \leq \varepsilon) \\ \wedge ([\text{ignite}] \implies \ell \leq 0.5 + \varepsilon) \\ \wedge ([\text{burn}] \implies \int \neg F \leq 2\varepsilon) \end{array} \right)$$

- **Case (iii):**  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{burn}] ; \text{true} \wedge \ell \leq 30$

From

$$[\text{burn}] \longrightarrow [\text{burn} \vee \text{idle}] \tag{Seq-4}$$

we can conclude

$$\mathcal{I}, \mathcal{V}, [b, e] \models ([\text{burn}] \vee [\text{burn}] ; \underbrace{[\text{idle}] ; \text{true}}_{\text{Case (ii)}}) \wedge \ell \leq 30.$$

By 3.15 and Case (ii),

$$\mathcal{I}, \mathcal{V}, [b, e] \models ((\int L \leq 2\varepsilon) \vee (\int L \leq 2\varepsilon)) ; (\int L \leq 2\varepsilon) \wedge \ell \leq 30.$$

hence

$$\mathcal{I}, \mathcal{V}, [b, e] \models \int L \leq 4\varepsilon.$$

Thus  $\boxed{\varepsilon \leq 0.25}$  is sufficient for Req-1 ( $\int L \leq 1$ ) **in this case.**

# Lemma 3.16 Cont'd

$$3.15: \text{GB-Ctrl} \implies \square \left( \begin{array}{l} ([\text{idle}] \implies f G \leq \varepsilon) \\ \wedge ([\text{purge}] \implies f G \leq \varepsilon) \\ \wedge ([\text{ignite}] \implies \ell \leq 0.5 + \varepsilon) \\ \wedge ([\text{burn}] \implies f \neg F \leq 2\varepsilon) \end{array} \right)$$

- **Case (iv):**  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{ignite}] ; \text{true} \wedge \ell \leq 30$

From

$$[\text{ignite}] \longrightarrow [\text{ignite} \vee \text{burn}] \quad (\text{Seq-3})$$

we can conclude

$$\mathcal{I}, \mathcal{V}, [b, e] \models ([\text{ignite}] \vee [\text{ignite}] ; \underbrace{[\text{burn}] ; \text{true}}_{\text{Case (iii)}}) \wedge \ell \leq 30.$$

By 3.15 and Case (iii),

$$\mathcal{I}, \mathcal{V}, [b, e] \models ((f L \leq 0.5 + \varepsilon) \vee (f L \leq 0.5 + \varepsilon)) ; (f L \leq 4\varepsilon) \wedge \ell \leq 30$$

hence

$$\mathcal{I}, \mathcal{V}, [b, e] \models f L \leq 0.5 + 5\varepsilon.$$

Thus  $\boxed{\varepsilon \leq 0.1}$  is sufficient for Req-1 ( $f L \leq 1$ ) **in this case.**

# Lemma 3.16 Cont'd

$$3.15: \text{GB-Ctrl} \implies \square \left( \begin{array}{l} ([\text{idle}] \implies \int G \leq \varepsilon) \\ \wedge ([\text{purge}] \implies \int G \leq \varepsilon) \\ \wedge ([\text{ignite}] \implies \ell \leq 0.5 + \varepsilon) \\ \wedge ([\text{burn}] \implies \int \neg F \leq 2\varepsilon) \end{array} \right)$$

- **Case (v):**  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{purge}] ; \text{true} \wedge \ell \leq 30$

From

$$[\text{purge}] \longrightarrow [\text{purge} \vee \text{ignite}] \quad (\text{Seq-2})$$

and 3.15 and Case (iv) we can conclude

$$\mathcal{I}, \mathcal{V}, [b, e] \models \int L \leq 0.5 + 6\varepsilon.$$

Thus  $\boxed{\varepsilon \leq \frac{1}{12}}$  is sufficient for Req-1 ( $\int L \leq 1$ ) **in this case.** □

## Lemma 3.16.

$$\models \exists \varepsilon \bullet \text{GB-Ctrl} \implies \underbrace{\square(\ell \leq 30 \implies \int L \leq 1)}_{\text{Req-1}}$$

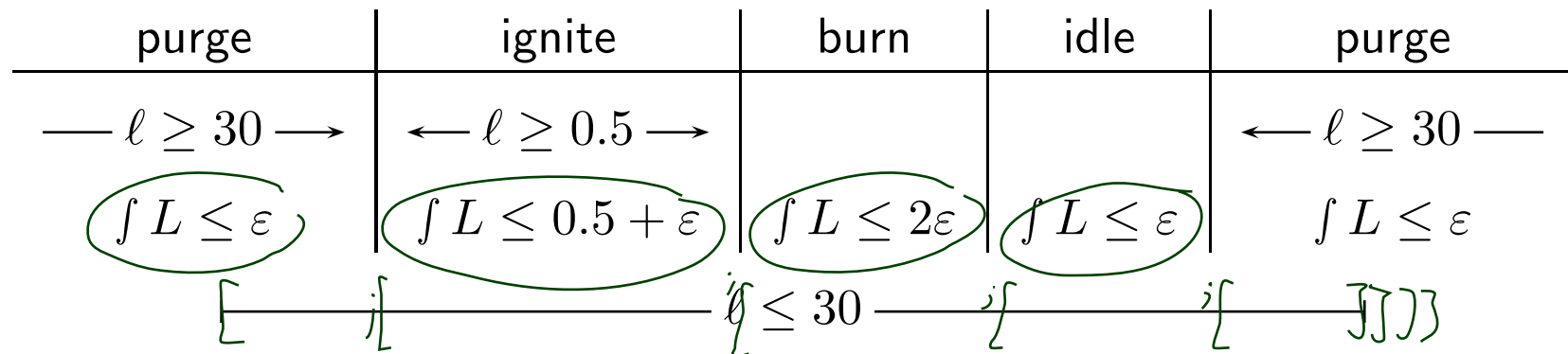
# Correctness Result

## Theorem 3.17.

$$\models \left( \text{GB-Ctrl} \wedge \varepsilon \leq \frac{1}{12} \right) \implies \text{Req}$$

### Recall:

- Req-1 =  $\square(l \leq 30 \implies fL \leq 1)$  implies Req.
- 3.15:  $\lceil \text{purge} \rceil \implies fL \leq \varepsilon$ ,  $\lceil \text{ignite} \rceil \implies fL \leq 0.5 + \varepsilon$ ,  $\lceil \text{burn} \rceil \implies fL \leq 2\varepsilon$ ,  $\lceil \text{idle} \rceil \implies fL \leq \varepsilon$ .



- Thus  $fL \leq 0.5 + 6\varepsilon$ , so a sufficient reaction time constraint is  $A(\varepsilon) := \varepsilon \leq \frac{1}{12}$ .

# Discussion

- We used only

‘Seq-1’, ‘Seq-2’, ‘Seq-3’, ‘Seq-4’,  
 ‘Prog-2’, ‘Syn-2’, ‘Syn-3’,  
 ‘Stab-2’, ‘Stab-5’, ‘Stab-6’.

What about

$$\text{Prog-1} = [\text{purge}] \xrightarrow{30+\varepsilon} [\neg\text{purge}]$$

for instance?

## Gas Burner Controller: The Complete Specification

### Controller: (local)

$\square \vee [\text{idle}] ; \text{true},$  (Init-1)  
 $[\text{idle}] \rightarrow [\text{idle} \vee \text{purge}]$  (Seq-1)  
 $[\text{purge}] \rightarrow [\text{purge} \vee \text{ignite}]$  (Seq-2)  
 $[\text{ignite}] \rightarrow [\text{ignite} \vee \text{burn}]$  (Seq-3)  
 $[\text{burn}] \rightarrow [\text{burn} \vee \text{idle}]$  (Seq-4)  
 $[\text{purge}] \xrightarrow{30+\varepsilon} [\neg\text{purge}]$  (Prog-1)  
 $[\text{ignite}] \xrightarrow{0.5+\varepsilon} [\neg\text{ignite}]$  (Prog-2)  
 $[\neg\text{purge}] ; [\text{purge}] \xrightarrow{\leq 30} [\text{purge}]$  (Stab-2)  
 $[\neg\text{ignite}] ; [\text{ignite}] \xrightarrow{\leq 0.5} [\text{ignite}]$  (Stab-3)  
 $[\text{idle} \wedge H] \xrightarrow{\varepsilon} [\neg\text{idle}]$  (Syn-1)  
 $[\text{burn} \wedge (\neg H \vee \neg F)] \xrightarrow{\varepsilon} [\neg\text{burn}]$  (Syn-2)  
 $[\neg\text{idle}] ; [\text{idle} \wedge \neg H] \rightarrow [\text{idle}]$  (Stab-1)  
 $[\text{idle} \wedge \neg H] \rightarrow_0 [\text{idle}]$  (Stab-1-init)  
 $[\neg\text{burn}] ; [\text{burn} \wedge H \wedge F] \rightarrow [\text{burn}]$  (Stab-4)

### Gas Valve: (output)

$\square \vee [\neg G] ; \text{true}$  (Init-4)  
 $[G \wedge (\text{idle} \vee \text{purge})] \xrightarrow{\varepsilon} [\neg G]$  (Syn-3)  
 $[\neg G \wedge (\text{ignite} \vee \text{burn})] \xrightarrow{\varepsilon} [G]$  (Syn-4)  
 $[G] ; [\neg G \wedge (\text{idle} \vee \text{purge})] \rightarrow [\neg G]$  (Stab-6)  
 $[\neg G \wedge (\text{idle} \vee \text{purge})] \rightarrow_0 [\neg G]$  (Stab-6-init)  
 $[\neg G] ; [G \wedge (\text{ignite} \vee \text{burn})] \rightarrow [G]$  (Stab-7)

### Heating Request: (input)

$\square \vee [\neg H] ; \text{true},$  (Init-2)

### Flame: (input)

$\square \vee [\neg F] ; \text{true},$  (Init-3)  
 $[F] ; [\neg F \wedge \neg\text{ignite}] \rightarrow [\neg F]$  (Stab-5)  
 $[\neg F \wedge \neg\text{ignite}] \rightarrow_0 [\neg F]$  (Stab-5-init)

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# Discussion

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- We used only

'Seq-1', 'Seq-2', 'Seq-3', 'Seq-4',  
'Prog-2', 'Syn-2', 'Syn-3',  
'Stab-2', 'Stab-5', 'Stab-6'.

What about

$$\text{Prog-1} = [\text{purge}] \xrightarrow{30+\epsilon} [\neg\text{purge}]$$

for instance?

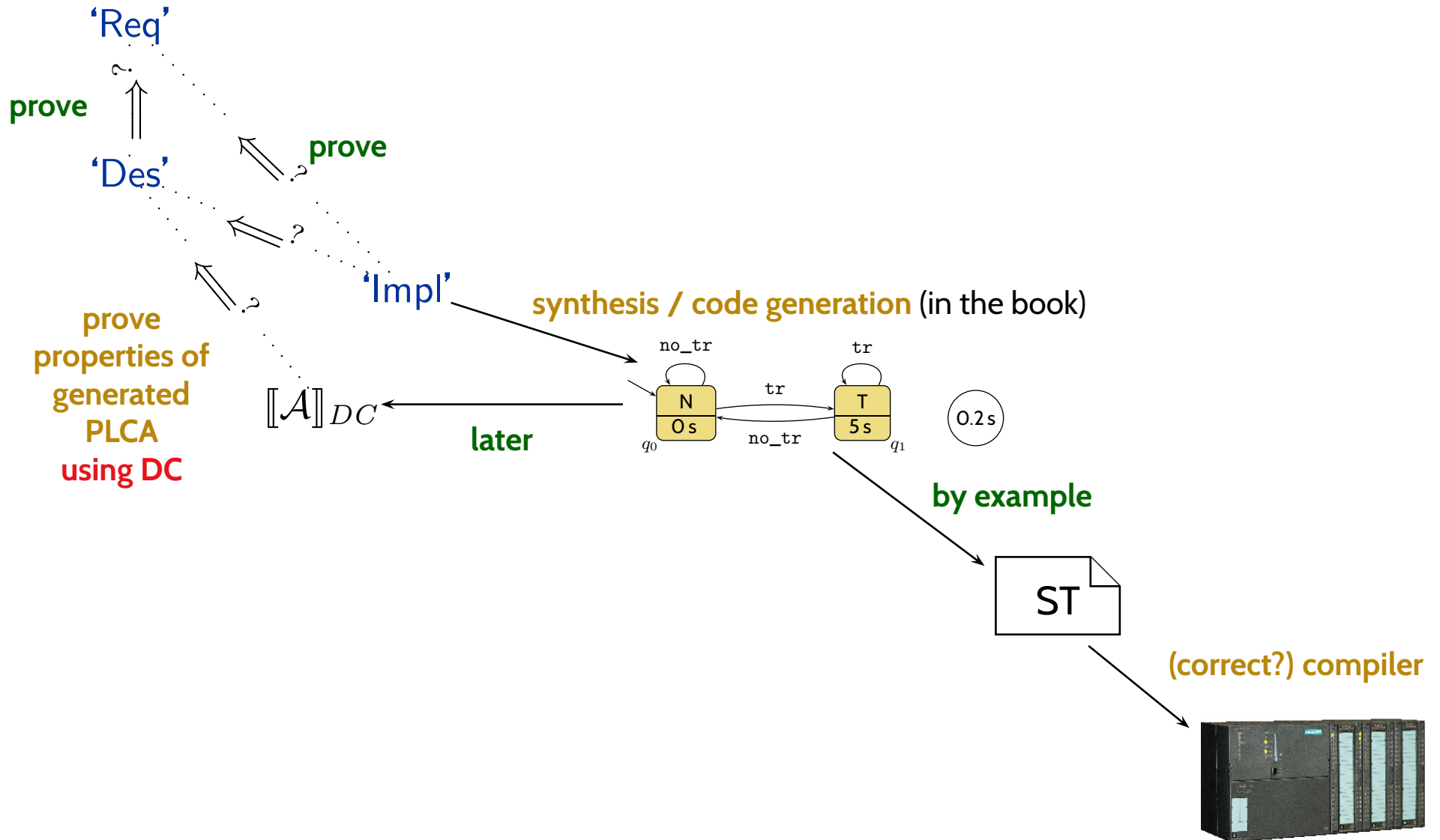
We only proved the **safety** property on leakage,  
we did not consider the (not formalised) **liveness** requirement:  
the controller **should do something** finally,  
e.g. heating requests should be served finally by trying an ignition.

- **Correctness Proof**  
for the Gas Burner Implementables
- 
- **Now where's the implementation?**
  - **Programmable Logic Controllers (PLC)**
    - How do they **look like**?
    - What's **special** about them?
    - The **read/compute/write** cycle of PLC
  - **Example: Stutter Filter**
    - **Structured Text** example
    - Other IEC 61131-3 programming languages
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    - **Example: Stutter Filter**
    - **PLCA Semantics** by example
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*Now Where's the Implementation?*

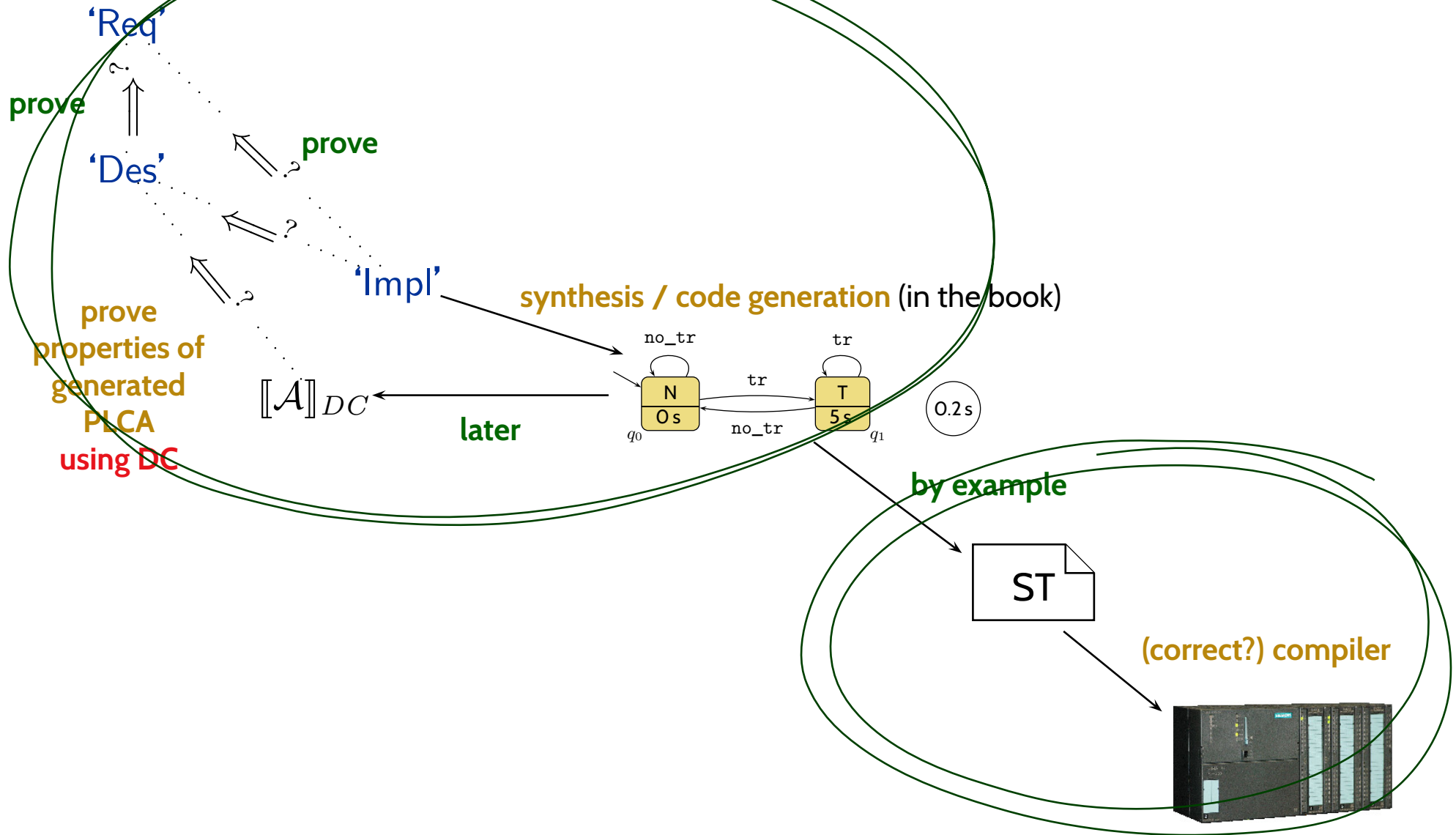
# The Plan

Full DC    DC Implementables    PLC-Automata    IEC 61131-3    Binary



# The Plan

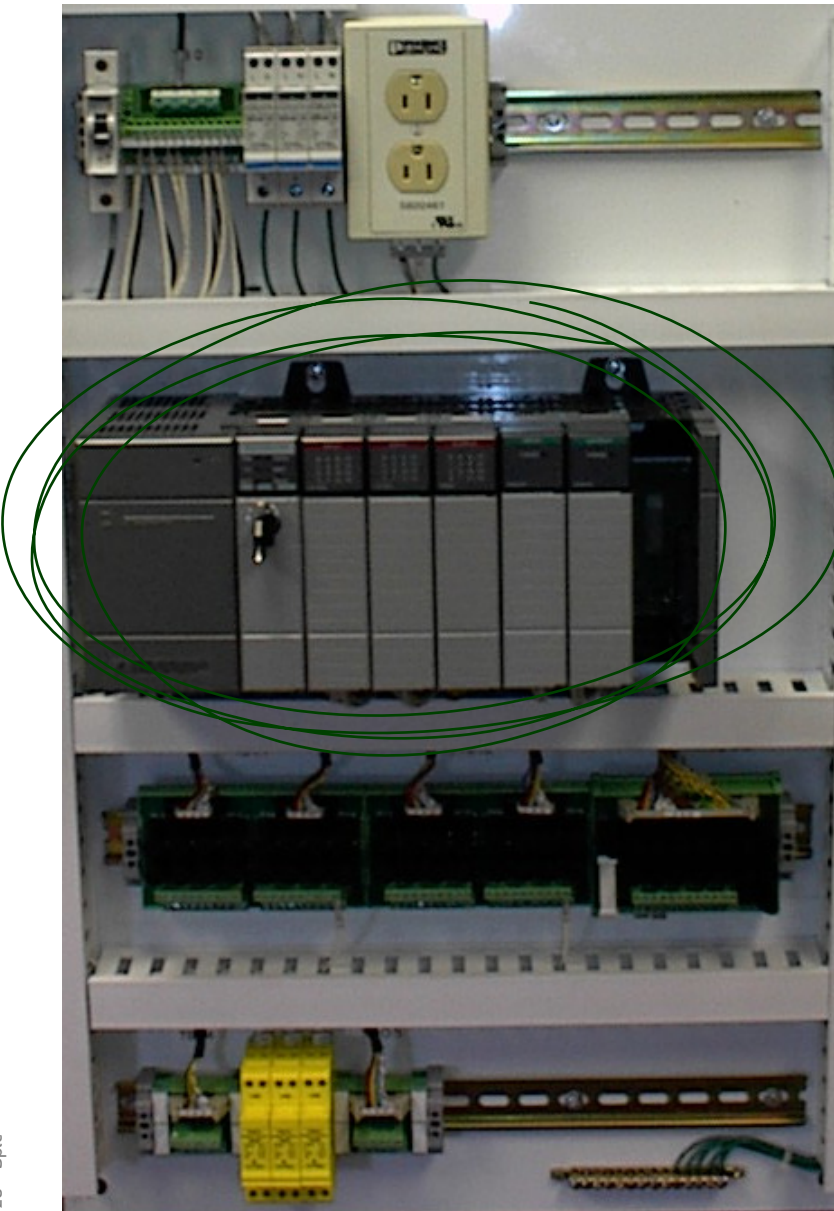
Full DC    DC Implementables    PLC-Automata    IEC 61131-3    Binary



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# *What is a PLC?*

# How do PLC look like?



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# What's special about PLC?



- microprocessor, memory, **timers**
- digital (or analog) I/O ports
- possibly RS 232, fieldbuses, networking
- robust hardware
- reprogrammable
- **standardised programming model** (IEC 61131-3)

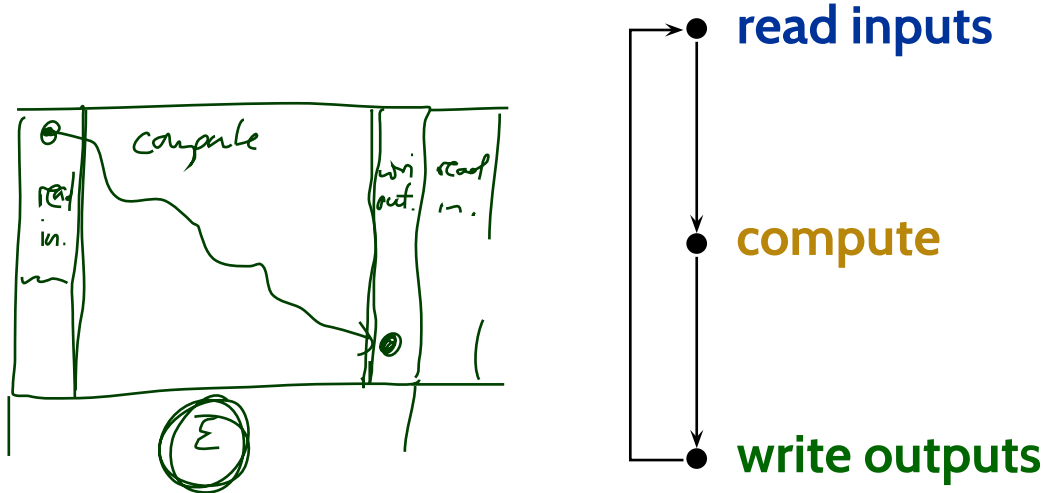
# Where are PLC employed?



- mostly **process automatisation**
  - production lines
  - packaging lines
  - chemical plants
  - power plants
  - electric motors, pneumatic or hydraulic cylinders
  - ...
- not so much: **product automatisation**, there
  - tailored or OTS controller boards
  - embedded controllers
  - ...

# How are PLC programmed?

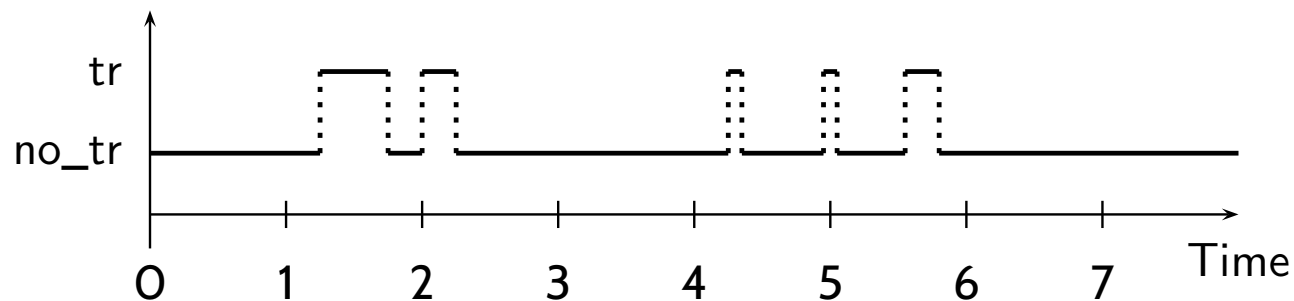
- PLC have in common that they operate in a cyclic manner:



- Cyclic operation is repeated until external interruption (such as shutdown or reset).
- Cycle time: typically a few milliseconds ([Lukoschus, 2004](#)).
- Programming for PLC means providing the “**compute**” part.
- Input/output values are available via designated local variables.

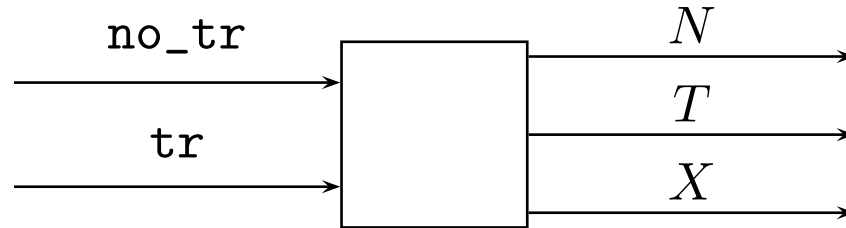
# How are PLC programmed, practically?

- **Example:** reliable, stutter-free train sensor.
  - Assume a track-side sensor which outputs:
    - `no_tr` – iff “no passing train”
    - `tr` – iff “a train is passing”
  - Assume that a change from “`no_tr`” to “`tr`” signals arrival of a train. (No spurious sensor values.)
- **Problem:** the sensor may **stutter**, i.e. oscillate between “`no_tr`” and “`tr`” multiple times.

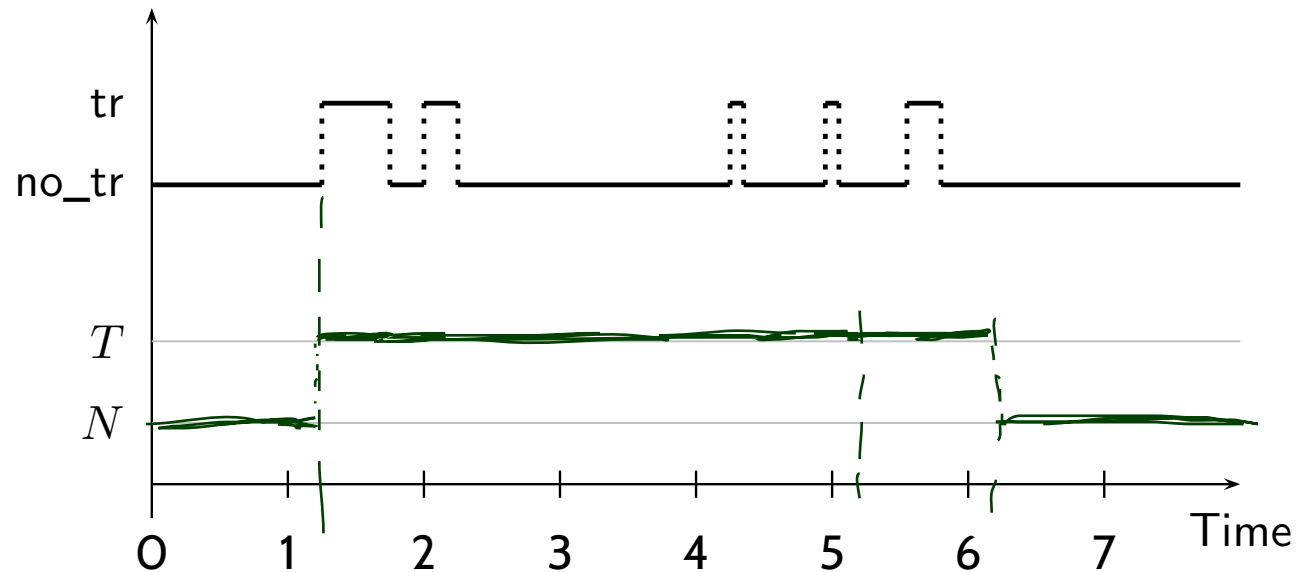


# Example: Stutter Filter

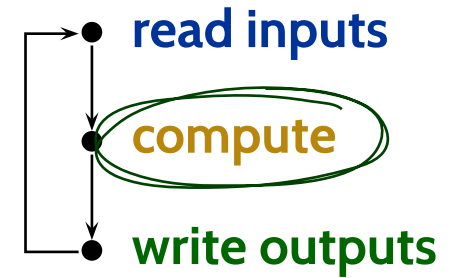
- **Idea:** a stutter **filter** with outputs  $N$  and  $T$ , for “no train” and “train passing” (and possibly  $X$ , for error).



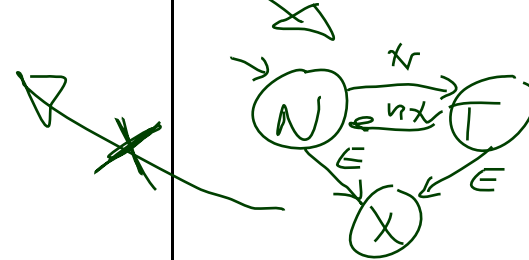
After arrival of a train, it should ignore “no\_tr” for 5 seconds.



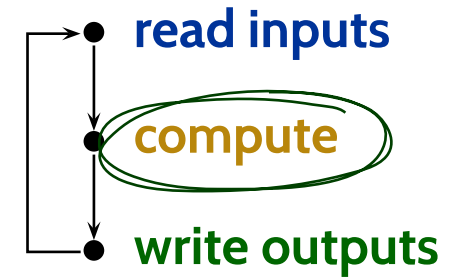
# How are PLC programmed, practically?



```
1 PROGRAM PLC_PRG_FILTER
2 VAR
3   state : INT := 0; (* 0:=N, 1:=T, 2:=X *)
4   tmr   : TP;
5 ENDVAR
6
7 IF state = 0 THEN
8   %output := N;
9   IF %input = tr THEN
10    state := 1;
11    %output := T;
12   ELSIF %input = Error THEN
13    state := 2;
14    %output := X;
15   ENDIF
16 ELSIF state = 1 THEN
17
18   tmr( IN := TRUE, PT := t#5.0s );
19   IF (%input = no_tr AND NOT tmr.Q) THEN
20    state := 0;
21    %output := N;
22    tmr( IN := FALSE, PT := t#0.0s );
23   ELSIF %input = Error THEN
24    state := 2;
25    %output := X;
26    tmr( IN := FALSE, PT := t#0.0s );
27   ENDIF
28 ENDIF
```



# How are PLC programmed, practically?



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26   ENDIF
27 ENDIF
28
```

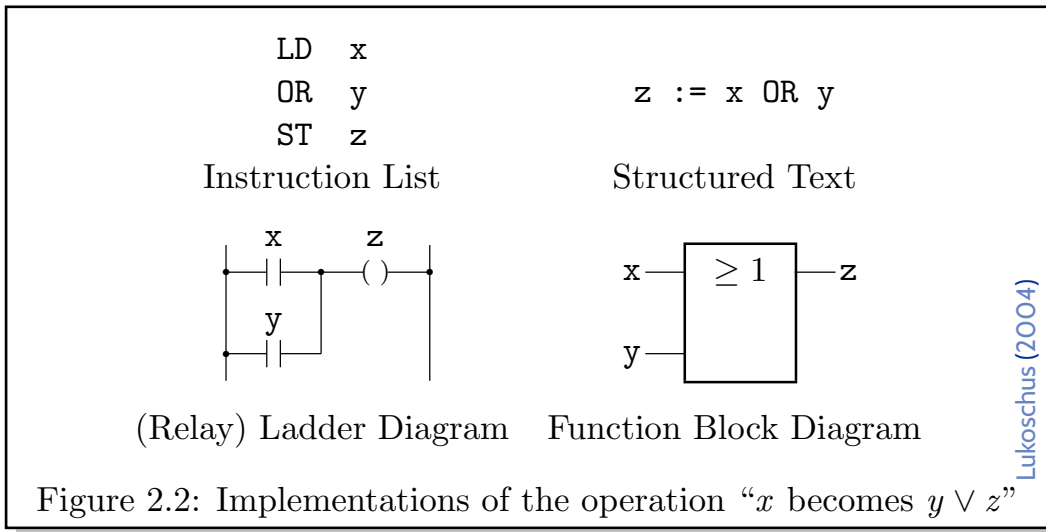
*declare timer tmr*

*intuitive semantics:*

- *do the assignment*
- *if assignment changed IN from FALSE to TRUE ("rising edge on IN") then set tmr to given duration (initially, IN is FALSE)*

*duration*

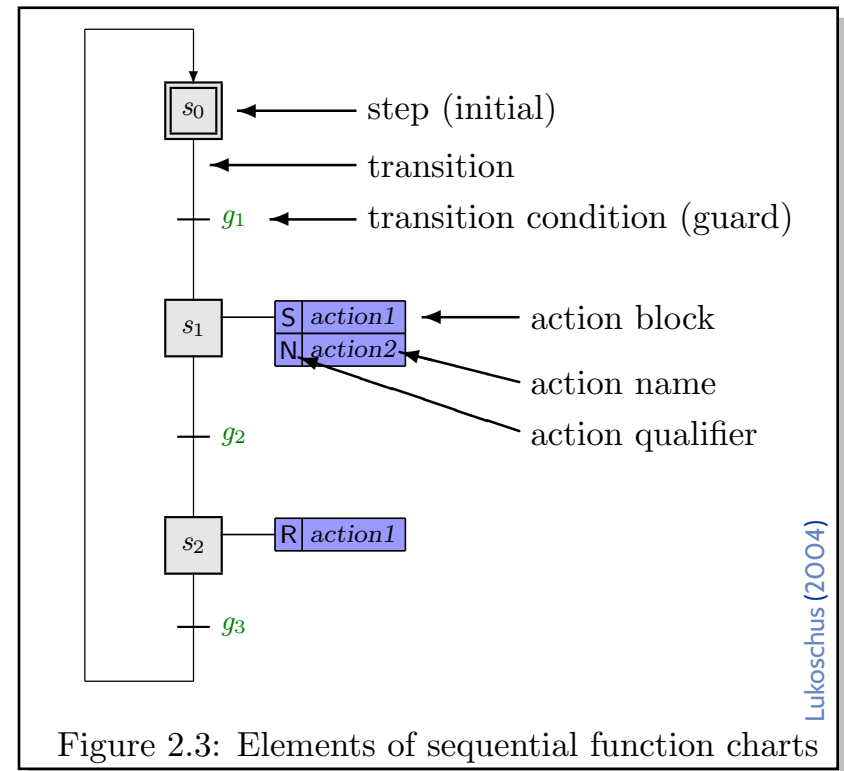
*TRUE: iff tmr is still running (here: if 5 s not yet elapsed)*



Tied together by

- Sequential Function Charts (SFC)

Unfortunate: deviations  
in semantics... [Bauer \(2003\)](#)





- **Correctness Proof**  
for the Gas Burner Implementables
- **Now where's the implementation?**
- **Programmable Logic Controllers (PLC)**
  - How do they **look like**?
  - What's **special** about them?
  - The **read/compute/write** cycle of PLC
- **Example: Stutter Filter**
  - **Structured Text** example
  - Other IEC 61131-3 programming languages
- **PLC Automata**
  - **Example: Stutter Filter**
  - **PLCA Semantics** by example
  - **Cycle time**

# Tell Them What You've Told Them...

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- We can **prove** the Gas Burner implementables **correct** by carefully considering its phases. ✓
- A **crucial aspect** is **reaction time**: ✓
  - Controller programs executed on some hardware platform do not react in **0-time**,
  - some platforms may be **too slow** to satisfy requirements. ✓
- **Programmable Logic Controllers (PLC)** are epitomic for real-time controller platforms:
  - have a **real-time clock** device,
  - can **read inputs** and **write outputs**,
  - can manage **local state**. ✓
- **PLC programs**
  - are executed in **read/compute/write** cycles,
  - have a **cycle-time** (possibly a watchdog).
- **PLC Automata** are a more abstract (than IEC 61131-3) way of describing and studying PLC programs.

# *References*

# References

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Bauer, N. (2003). *Formale Analyse von Sequential Function Charts*. PhD thesis, Universität Dortmund.

Lukoschus, B. (2004). *Compositional Verification of Industrial Control Systems*. PhD thesis, Christian-Albrechts-Universität zu Kiel.

Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.