## Software Design, Modelling and Analysis in UML

Lecture 02: Semantical Model

#### 2011-10-26

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### Contents & Goals

#### Last Lecture:

- Motivation: model-based development of things (houses, software) to cope with complexity, detect errors early
- Model-based (or -driven) Software Engineering
- UML Mode of the Lecture: Blueprint.

#### This Lecture:

- Educational Objectives: Capabilities for these tasks/questions:
  - Why is UML of the form it is?
  - Shall one feel bad if not using all diagrams during software development?
  - What is a signature, an object, a system state, etc.? What's the purpose of signature, object, etc. in the course?
  - How do Basic Object System Signatures relate to UML class diagrams?

#### • Content:

- Brief history of UML
- Course map revisited
- Basic Object System Signature, Structure, and System State

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Why (of all things) UML?

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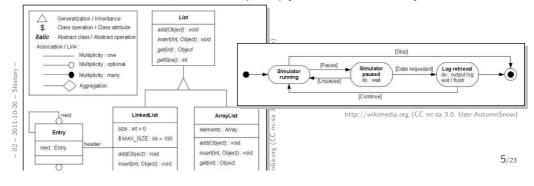
- Note: being a **modelling** languages doesn't mean being graphical (or: being a visual formalism [Harel]).
- For instance, [Kastens and Büning, 2008] also name:
  - Sets, Relations, Functions
  - Terms and Algebras
  - Propositional and Predicate Logic
  - Graphs
  - XML Schema, Entity Relation Diagrams, UML Class Diagrams
  - Finite Automata, Petri Nets, UML State Machines
- **Pro**: visual formalisms are found appealing and easier to grasp. Yet they are not necessarily easier to write!

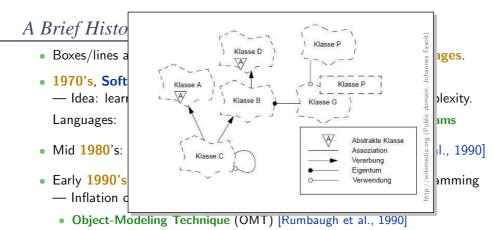
• **Beware**: you may meet people who dislike visual formalisms just for being graphical — maybe because it is easier to "trick" people with a meaningless picture than with a meaningless formula.

More serious: it's maybe easier to misunderstand a picture than a formula.

#### A Brief History of UML

- Boxes/lines and finite automata are used to visualise software for ages.
- 1970's, Software Crisis<sup>TM</sup>
   — Idea: learn from engineering disciplines to handle growing complexity.
  - Languages: Flowcharts, Nassi-Shneiderman, Entity-Relation Diagrams
- Mid 1980's: Statecharts [Harel, 1987], StateMate<sup>™</sup> [Harel et al., 1990]
- Early 1990's, advent of Object-Oriented-Analysis/Design/Programming
   Inflation of notations and methods, most prominent:
  - Object-Modeling Technique (OMT) [Rumbaugh et al., 1990]





• Booch Method and Notation [Booch, 1993]

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  - Booch Method and Notation [Booch, 1993]
  - Object-Oriented Software Engineering (OOSE) [Jacobson et al., 1992]

Each "persuasion" selling books, tools, seminars...

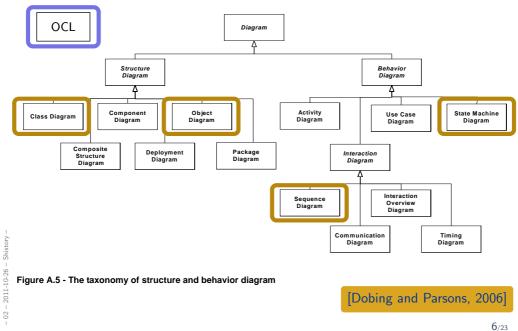
• Late 1990's: joint effort UML 0.x, 1.x

Standards published by Object Management Group (OMG), "international, open membership, not-for-profit computer industry consortium".

• Since 2005: UML 2.x

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## UML Overview [OMG, 2007b, 684]



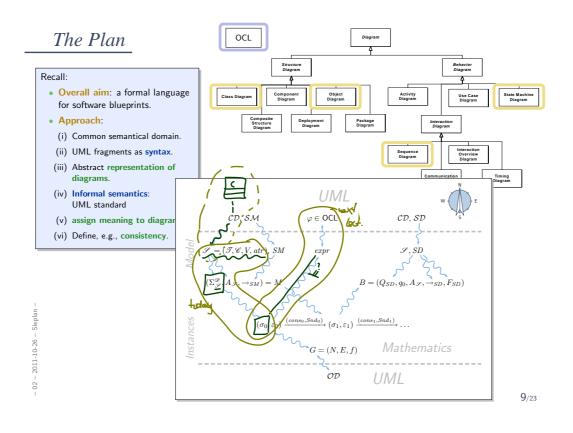
- Easily writeable, readable even by customers
- Powerful enough to bridge the gap between idea and implementation
- Means to tame complexity by separation of concerns ("views")
- Unambiguous
- Standardised, exchangeable between modelling tools
- UML standard says how to develop software
- Using UML leads to better software
- ...

# We will see...

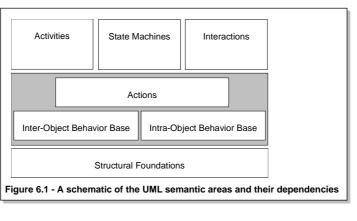
Seriously: After the course, you should have an own opinion on each of these claims. In how far/in what sense does it hold? Why? Why not? How can it be achieved? Which ones are really only hopes and expectations?  $\dots$ ?

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Course Map Revisited



UML: Semantic Areas

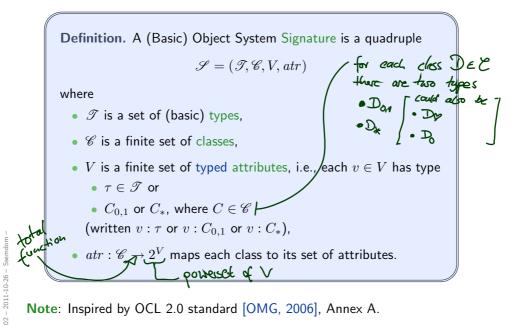


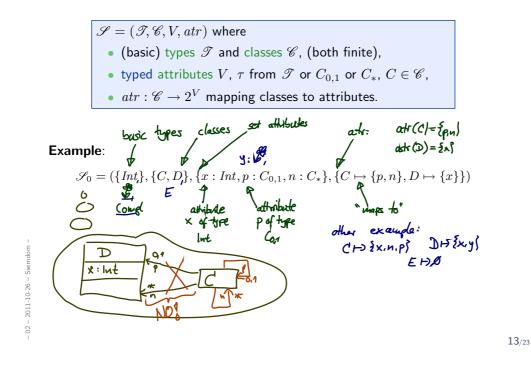
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Common Semantical Domain

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## Basic Object System Signature





Basic Object System Signature Another Example

$$\begin{split} \mathscr{S} &= (\mathscr{T}, \mathscr{C}, V, atr) \text{ where} \\ \bullet \text{ (basic) types } \mathscr{T} \text{ and classes } \mathscr{C}\text{, (both finite),} \\ \bullet \text{ typed attributes } V, \ \tau \text{ from } \mathscr{T} \text{ or } C_{0,1} \text{ or } C_*, \ C \in \mathscr{C}\text{,} \\ \bullet \ atr : \mathscr{C} \to 2^V \text{ mapping classes to attributes.} \end{split}$$

Example:

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Rehaue!

Definition. A Basic Object System Structure of S = (T, C, V, atr)
is a domain function D which assigns to each type a domain, i.e.
τ ∈ T is mapped to D(τ),
C ∈ C is mapped to an infinite set D(C) of (object) identities. Note: Object identities only have the "=" operation; object identities of different classes are disjoint, i.e. ∀C, D ∈ C : C ≠ D → D(C) ∩ D(D) = Ø.
C<sub>\*</sub> and C<sub>0,1</sub> for C ∈ C are mapped to 2<sup>D(C)</sup>.
We use D(C) to denote U<sub>C∈C</sub> D(C); analogously D(C<sub>\*</sub>).

**Note**: We identify objects and object identities, because both uniquely determine each other (cf. OCL 2.0 standard).

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## Basic Object System Structure Example

Wanted: a structure for signature

$$\mathscr{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$

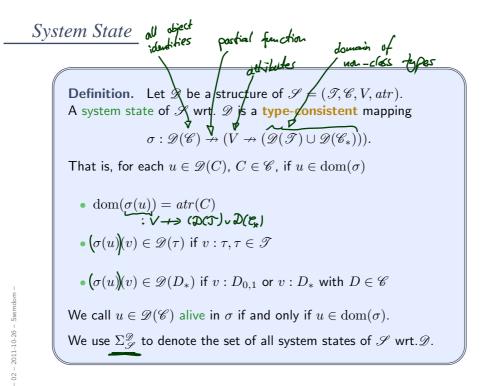
Recall: by definition, seek a  $\mathscr{D}$  which maps

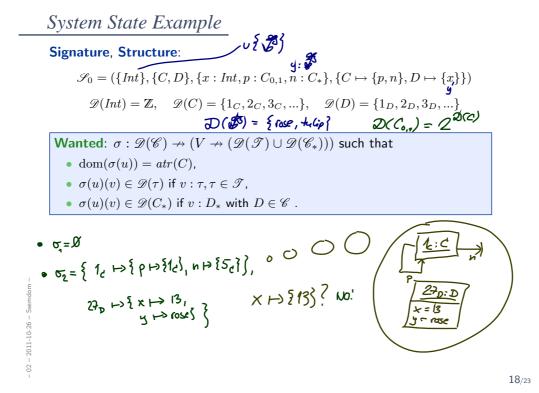
- $\tau \in \mathscr{T}$  to some  $\mathscr{D}(\tau)$ ,
- $c \in \mathscr{C}$  to some identities  $\mathscr{D}(C)$  (infinite, disjoint for different classes),
- $C_*$  and  $C_{0,1}$  for  $C \in \mathscr{C}$  to  $\mathscr{D}(C_{0,1}) = \mathscr{D}(C_*) = 2^{\mathscr{D}(C)}$ .

 $\mathcal{D}(Int) = \mathbb{Z} \quad (\text{could also be } \{-100, \dots, 33, 100\}$  $\mathcal{D}(C) = \mathbb{IN}^{+} \times \{C\} \cong \{\mathbb{I}_{C}, \mathbb{Z}_{C}, \mathbb{Z}_{C}, \dots\}$  $\mathcal{D}(D) = \mathbb{IN}^{+} \times \{D\} \cong \{\mathbb{I}_{D}, \mathbb{Z}_{D}, \mathbb{Z}_{D}, \mathbb{Z}_{D}, \dots\}$  $\mathcal{D}(C_{0,1}) = \mathcal{D}(C_{*}) = \mathbb{2}^{\mathcal{D}(C)}$  $\mathcal{D}(D_{0,1}) = \mathcal{D}(D_{*}) = \mathbb{2}^{\mathcal{D}(D)}$ 

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## System State Example

#### Signature, Structure:

$$\begin{aligned} \mathscr{S}_0 &= (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\}) \\ \mathscr{D}(Int) &= \mathbb{Z}, \quad \mathscr{D}(C) = \{1_C, 2_C, 3_C, \ldots\}, \quad \mathscr{D}(D) = \{1_D, 2_D, 3_D, \ldots\} \end{aligned}$$

$$\begin{split} & \textbf{Wanted: } \sigma: \mathscr{D}(\mathscr{C}) \nrightarrow (V \nrightarrow (\mathscr{D}(\mathscr{T}) \cup \mathscr{D}(\mathscr{C}_*))) \text{ such that} \\ & \bullet \ \operatorname{dom}(\sigma(u)) = \operatorname{atr}(C), \\ & \bullet \ \sigma(u)(v) \in \mathscr{D}(\tau) \text{ if } v: \tau, \tau \in \mathscr{T}, \end{split}$$

•  $\sigma(u)(v) \in \mathscr{D}(C_*)$  if  $v: D_*$  with  $D \in \mathscr{C}$ .

• Concrete, explicit:

$$\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, 1_D \mapsto \{x \mapsto 23\}\}.$$

• Alternative: symbolic system state

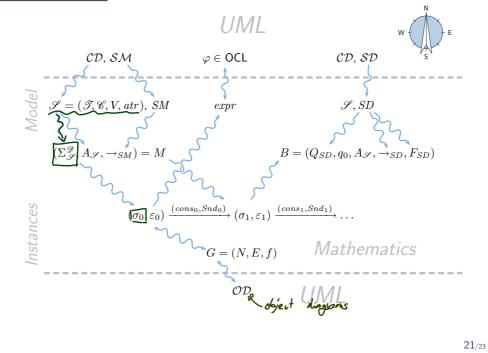
$$\sigma = \{c_1 \mapsto \{p \mapsto \emptyset, n \mapsto \{c_2\}\}, c_2 \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, d \mapsto \{x \mapsto 23\}\}$$

assuming  $c_1, c_2 \in \mathscr{D}(C)$ ,  $d \in \mathscr{D}(D)$ ,  $c_1 \neq c_2$ .

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You Are Here.





References

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